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GENERATION AND REDUCTION OF THE DATA FOR THE
ULYSSES GRAVITATIONAL WAVE EXPERIMENT

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IFSI-87-20

December 1987

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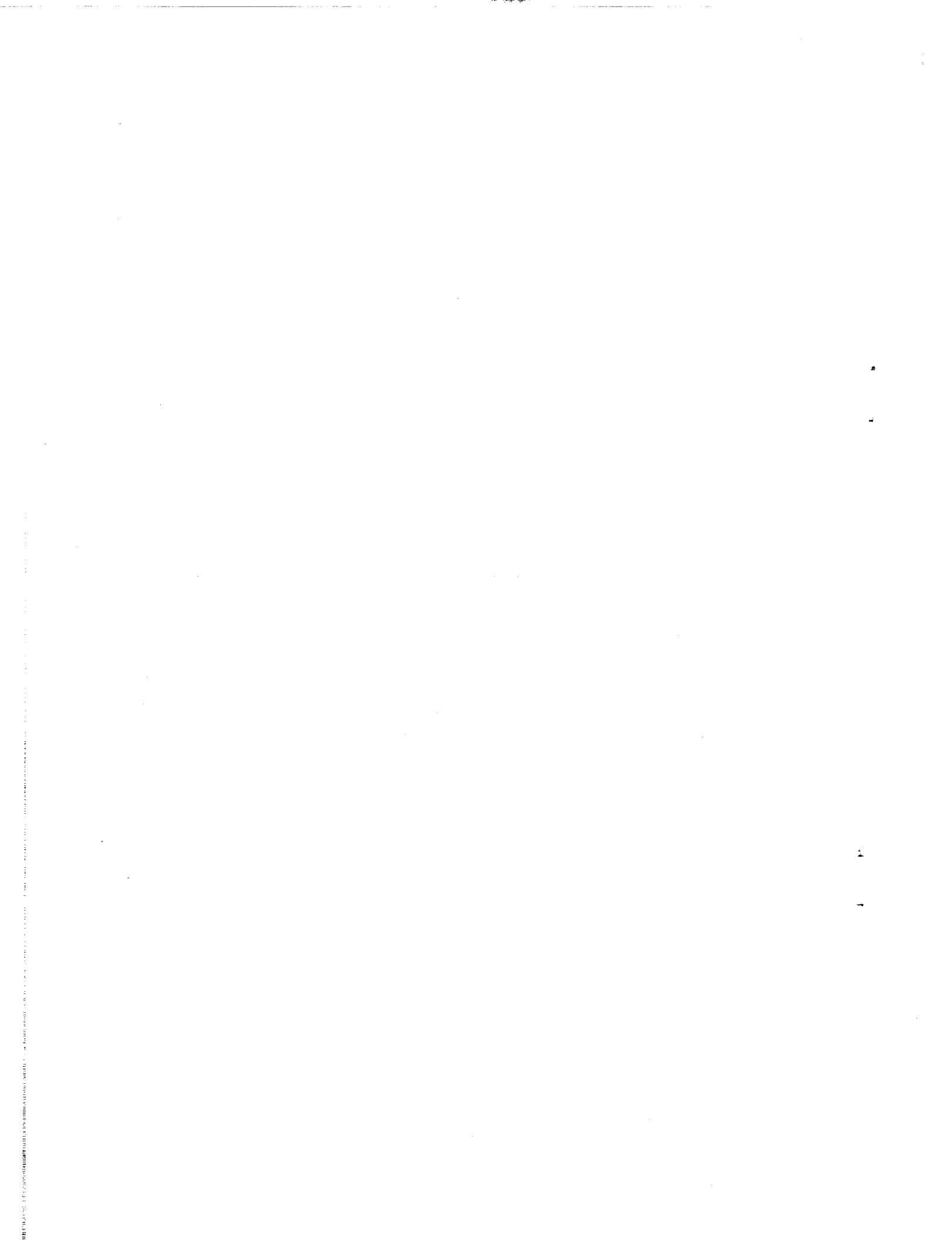
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(NASA-CR-184576) GENERATION AND REDUCTION
OF THE DATA FOR THE ULYSSES GRAVITATIONAL
WAVE EXPERIMENT (Jet Propulsion Lab.) 77 p

NASA-12273

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G6/b1 0175057



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ULYSSES GRAVITATIONAL WAVE EXPERIMENT

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SUMMARY

We describe a procedure for the generation and reduction of the radiometric data known as 'REGRES' files. These data are a current output of NASA's Orbit Determination Program. The software package was developed in view of the data analysis of the gravitational wave experiment, (GWE) planned for the European spacecraft 'Ulysses'.

INTRODUCTION

Doppler tracking of interplanetary spacecraft is routinely performed by the stations of NASA's Deep Space Network (DSN). An electromagnetic carrier of highly stable frequency is sent from a ground station to a spacecraft, which retransmits it back coherently to the Earth by means of a transponder.

The presently used radio link configurations for precision Doppler tracking are of two types: in the first one, called 'two-way' operation, the same station both transmits and receives the radio signal, in the second one, called 'three-way', the transmitting and receiving station are different. The signal is usually transmitted in S band (2.1 GHz) and received both in S and X band (8.4 GHz).

We call Doppler residual the quantity obtained by subtracting the measured frequency shift of the carrier to the predicted one. In the REGRES data, the predictions are obtained *a posteriori* by means of a regression method: the received radiometric data are used to improve the spacecraft ephemeris in order to minimise the least square deviation between the observables and the predictions.

In this paper we report a description of the REGRES data generation and of the software we have developed to reduce and display the data. This software has been applied to the analysis of four days (DOY 308 - DOY 313, 1980) of REGRES data relative to the Voyager I spacecraft.

The software package was implemented on an HP-1000F computer, with an RTE-6-VM operative system. The graphical unit was an HP-9872T plotter. A general purpose graphical routine, developed at IFSI-CNR, was used to plot output data.

REGRES FILE GENERATION

REGRES files are a current output of the Orbit Determination Program (ODP). The volume and the structure of REGRES files are not fixed, but depend on the way the ODP is run. Standard references on the subject are (Moyer, 1971) and (Khatib et al., 1972). ODP is actually a set of many links, which, to some extent, may be run independently. Its functions are integrated by a number of allied programs, the most important of which is DPTRAJ. The process which leads to the computation of the trajectory of the spacecraft is described in the following.

The fundamental quantities handled by the ODP are:

$\underline{X}=(\underline{r}, \dot{\underline{r}})$: spacecraft state vector, i.e. position and velocity of the spacecraft with respect to a center of integration (usually the baricenter of a celestial body).

$\underline{q}=(\underline{X}_0, \underline{a})$: parameter vector, containing the initial state of the spacecraft (\underline{X}_0) and a set (\underline{a}) of physical parameters (see below) needed for the integration of the equations of motion.

\underline{z} : vector of observable quantities (Doppler, range, angle, Δ DOR).

The main physical parameters \underline{a} are:

- the gravitational parameters $\mu_i = GM_i$ of Sun, planets and satellites of the solar system;
- the coefficients of the harmonic expansion of the

- planets' gravitational potential;
- the quantities used in modelling the probe acceleration due to small forces and manoeuvres;
- atomic station time \rightarrow UTC conversion parameter;
- coordinates of the tracking stations;
- the relativistic parameter γ .

Many other quantities may be used, depending on the particular spacecraft: there are parameters relating to atmospheric models, mass anomalies, gas leaks, solar radiation pressure, etc.

The vector \underline{a} is usually stored as a part of a file called Generalised Input File (GIN file), characterising the physical world in which the probe moves.

The ODP not only performs the integration of the equations of motion, but also allows the redeterminations of the parameters \underline{g} and, therefore, the determination of a better state vector $\underline{X}(t)$. This goal is obtained by comparing predictions and observations in a regressive analysis made up of several steps.

STEP 1 PATH-VARY (or PVDRIKE)

This link has actually a twofold purpose and may be separated for clarity into two sub-units (PATH and VARY). PATH integrates the equations of motion of the probe, starting from given injection parameters \underline{X}_0 and physical parameters \underline{a} . The probe acceleration results from the following contributions:

- Newtonian gravitational forces (leading term) from the relevant celestial bodies.
- Oblatenesses of planets.
- Mascons.
- Relativistic effects.
- Solar radiation pressure.
- Attitude control.

- Orbital manoeuvres.
- Atmospheric drag (in case of planetary encounter).

The center of integration may be any planet, or center of mass of planetary system (i.e. planet with satellites). The output of PATH is a propagation of the initial state vector \underline{X} along the trajectory as a function of time and of the parameters \underline{q} :

$$\underline{X} = \underline{X}(t, \underline{q})$$

Its output $\underline{X}(t)=(\underline{r}(t), \dot{\underline{r}}(t))$ may be stored in the Probe Ephemeris Tape (PET). It is also used as input to the program PREDIX which provides observable predictions to the tracking stations. These predictions are used to generate the pseudoresiduals contained in the Archival Tracking Data Files (ATDF).

The other subunit (VARY) integrates the variational equations

$$\frac{\partial \ddot{\underline{r}}}{\partial \underline{q}} = \frac{\partial \ddot{\underline{r}}}{\partial \underline{r}} \frac{\partial \underline{r}}{\partial \underline{q}} + \frac{\partial \ddot{\underline{r}}}{\partial \dot{\underline{r}}} \frac{\partial \dot{\underline{r}}}{\partial \underline{q}} + \left[\frac{\partial \ddot{\underline{r}}}{\partial \underline{q}} \right] \quad \underline{r}, \dot{\underline{r}} = \text{const}$$

$$\ddot{\underline{Z}} = A\underline{Z} + B\dot{\underline{Z}} + C \quad \underline{Z} = \frac{\partial \underline{r}}{\partial \underline{q}}$$

whose solution gives \underline{Z} and $\dot{\underline{Z}}$ as functions of time. These quantities are needed in the subsequent step (REGRES) to get the partial derivatives of the observable quantities with respect to the parameters. The matrices A, B and C are obtained from the equations of celestial mechanics.

STEP 2 (REGRES)

In this step, the regression partial derivatives of the observables (Doppler, range, angle) with respect to the parameters g are formed. The regression partial derivatives are needed to adjust the quantities \underline{x}_0 and \underline{a} in order to obtain a better estimate of the spacecraft trajectory (i.e. better residuals).

To this end, for each acquired value of the observable r at the reception time t_3 , the corresponding ground transmission time t_1 and spacecraft reception time t_3 are computed. The times t_1 and t_2 are obtained by solving the light time problem in the metric of the solar system baricenter. For each leg (uplink and downlink) the transmission and reception times are given by (neglecting terms of order $1/c^5$):

$$t_{\text{rec}} - t_{\text{trans}} = \frac{r_{ij}}{c} + \frac{1+\gamma}{c^3} \mu_s \ln \frac{(r_i + r_j + r_{ij})}{(r_i + r_j - r_{ij})}$$

where

$$r_i = || \underline{r}_i(t_{\text{trans}}) ||$$

$$r_j = || \underline{r}_j(t_{\text{rec}}) ||$$

$$r_{ij} = || \underline{r}_j(t_{\text{rec}}) - \underline{r}_i(t_{\text{trans}}) ||$$

$$\mu_s = GM_s = \text{gravitational parameter of the Sun}$$

$$\gamma = \text{post newtonian parameter (in general relativity } \gamma = 1)$$

The vectors \underline{r} have origins in the solar system baricenter. In the last version of REGRES bending terms as

well as Jupiter and Saturn terms are included.

The solution of the light time problem must be performed for each acquired point, and requires therefore considerable computer time.

The regression derivatives $\partial \underline{r} / \partial q$ are then formed by considering that the observable \underline{r} is a function of the state vectors of the Earth stations and the spacecraft;

$$Z = Z[\underline{X}_{st}(t_3, q), \underline{X}_{sc}(t_2, q), \underline{X}_{st}(t_1, q); q]$$

It may be seen that the partial derivatives $\partial \underline{r} / \partial q$ are actually the sum of many terms, originating from explicit and implicit dependence of Z on the parameter vector. We refer to (Moyer, 1982) for a detailed discussion of the subject. Here we just point out that the solution of the variational equations, which provides the quantity $\partial \underline{X}_{sc} / \partial q$, is required for the computation of $\partial Z / \partial q$.

A typical REGRES output file contains:

- a) values of the parameters q for which partials have been computed
- b) the selected observables and their residuals
- c) the selected partial derivatives $\partial \underline{r} / \partial q$.

It must be noted that at this step the parameters q are divided into two groups: "solve-for" parameters, for which new values are computed; "consider" parameters, which are not corrected but whose errors are taken into account in the computation of the errors for the "solve-for" parameters.

STEP 3 (ACCUME-SOLVE)

These two links use the partials obtained from the previous step to compute the parameter vector q and

its covariance matrix. With the new q's, a new GIN file may be created, and a new iteration, PV, REGRES, ACCUME, SOLVE (PVRAS), may be started.

The REGRES file which we analysed has not been generated by the complete sequence PVRAS, which is complicated and unnecessary for our purposes. The link REGRES was run in the so called "simulation mode", i.e. using already existing PV and GIN files and bypassing the computation of the partial derivatives $\frac{\partial z}{\partial q}$. The following steps have been performed to get the final REGRES file:

- a) select the GIN file to be used, which contains an initial state vector ($\underline{r}_0, \dot{\underline{r}}_0$) of the spacecraft and a set of physical parameters \underline{a} that already gave satisfactory residuals.
- b) select the corresponding PV file (containing probe ephemeris)
- c) select the file (ATDF or IDR) containing the observable quantities for which the residuals have to be computed (we actually used the same ATDF which was previously analysed at Frascati).
- d) run the program STRIPPER which, starting from an ATDF or IDR, generates an OD file (a file which can be used as an input to REGRES)
- e) run REGRES in the "simulation mode", using PV, GIN and OD files as input (together with the ephemeris of the bodies of the solar system).

The output of the step (e) is the required REGRES file.

SOFTWARE

In this section we report on the software package implemented on the HP1000F System at CNR-Frascati to handle the REGRES files.

These data, generated by an Univac 1108 System at JPL and stored on magnetic tape, have been converted using the Univac computer of the University of Rome in ASCII characters files stored on magnetic tape. The list of this Fortran program (named UNIHP) is shown in appendix B.

The main program implemented on the HP1000F (named DECODEREGRESS) decodes the REGRES data (ASCII characters) and selects the relevant items for the GWE data. The format of the output data (called STANDARD format throughout the paper) is described in (Iess and Armstrong 1985).

The software package is completed by a set of programs for the display and validation of the data and for the storage of Doppler residuals (our observable) in the HP disk memory. These programs are named: STATREGRESS, PLOTREGRESS and FFREGRESS.

STATREGRESS reads the STANDARD tapes and produces an output list for each day of data. This list contains hourly and total number of samples for each active station, band and mode.

PLOTREGRESS provides plots of the STANDARD tapes.

In order to simplify the access to the data, the STANDARD files can be copied on a disk using the FFREGRESS program. Each disk file contains the data relative to a single pass.

The program listings are reported in Appendix B. In the following we report a description of the software.

DECODEREGRES

DECODEREGRESS reads the REGRES tapes in ASCII format, selects the items relevant to the GWE and generates the STANDARD tapes.

DATA STRUCTURE

INPUT

BUFFER DIMENSION: ISK(40, 100)

RECORD LENGTH: 8000 characters

RECORD FORMAT: Each data record is composed of 100 cards of 80 characters each. The 80 characters of each card have the following meaning:

char. 1-5 : measurement group identifier N1, ranging from to 99999

char. 6-8 : card identifier N2, ranging from 1 to 100

char. 9-32 : data value, written in the format F24. 18

char. 33-56: as above

char. 57-80: as above

DATA FORMAT: In the original tapes generated at JPL, twenty quantities were associated to each Doppler data acquisition (see tab. 1). We will refer to this set of 20 quantities as to a "measurement". Therefore each record contains 15 measurements (i. e.: $3*100/20$), (see tab. 2). A data block is defined as a set of 40 measurements. The block identifier number N1, which appear in tab. 2, refers to the record generated at JPL with the Univac routine NTRAN.

See tab. 3 for an example of ISK (40,100) record.

OUTPUT

The output data, stored on magnetic tapes, are structured as a sequence of fixed length records with eof.

BUFFER DIMENSION: LMAT(160,15)

RECORD LENGTH: 2400 double integers number, i.e. 4800
16-bit words.

RECORD FORMAT: Each of the 160 rows contains 15 double
integer items.

DATA FORMAT: Each row contains information about one measurement in both bands (S and X). Tab. 4 shows the data structure of the STANDARD records.

In tab. 5 we report, the items of the REGRES tapes generated at JPL and their corresponding items in the STANDARD records. Tab. 6 shows an example of STANDARD record (they e.c. refers to the same REGRES data in tab. 3).

ALGORITHM

The program reads in sequence the ISK(40,100) records. The 20 quantities corresponding to a single measurement are transferred in the INTEGER*4 buffer ISK1(240). This buffer is decoded and the relevant items of each measurement are transferred in a second INTEGER*4 buffer LMAT(160,15). It is important to note that two subsequent measurements in input usually refers to the S and X band respectively. In order to properly fill the eighth column of the matrix LMAT (S-3/11X), the program requires that S-band datum must precede the X-band datum in the input data. In fig. 2a and 2b is reported the flowchart of the program.

The program is structured as a main routine, managing the input data buffer, and a subroutine, managing the output buffer. Those two program segments are now described in more detail, referring to fig. 2a and 2b.

MAIN PROGRAM

- 1) INFORMATION FOR INPUT/OUTPUT
 - 1a) options and parameters for the job:
sequential number of the required initial REGRES

record, sequential number of the required final
REGRES record;
tape logical unit number;
etc.

1b) search for initial record to analyse

2) READ A ISK (40.100) RECORD
this step is made using the system routine XTAPE
(EXEC)
check on the record length
eof causes jump to step #8
read error causes jump to next record

3) TEST FOR COLUMN IDENTIFIER
if the block identifier is changed, the program
resets the decodifying buffer pointer IP. This step
is needed to eliminate the free item present at
every changing group

4) DECODIFICATION AND STORAGE OF THE DATA
this step is performed by the subroutine CONTROLLO
which transfers and decodes the data

5, 6, 7) REPEAT STEPS 1 TO 4 FOR ALL REQUIRED RECORDS
AND TAPES

8) FINAL OPERATIONS
8a) stores the last data in memory
8b) writes eof on STANDARD tape and rewinds the tapes
8c) prints information on the work just carried out

9) STOP

STATREGRESS

This program reads the STANDARD tapes and produces an output list for each day. The list contains hourly and total number of samples for each active station, band and mode. An example of an output list is reported in tab. 7.

ALGORITHM

The input data are contained in the STANDARD files generated by DECODEREGRESS. The algorithm uses a buffer of sample counters structured as a matrix 48*24. Each row represents one of the combinations of 6 DSN, stations 4 tracking modes and 2 bands, while the 24 columns represent the hours of the day. The identification of the sample counter for a given DSN station, band, mode and hour of day combination is given by:

```
ROW = ( S - 1 ) * 8 + ( M - 1 ) * 2 + B  
COL = HOUR OF DAY
```

where B is 1 or 2 for S or X band respectively M represent the 4 different radio link modes, while S=1, 2, 3, 4, 5, 6 represents the six DSS: 12, 14, 42, 43, 61 and 63 respectively. The decodification of the row number can be made as follows:

```
STATION = INT ( ( ROW - 1 ) / 8 ) + 1  
BAND = ROW's PARITY  
MODE = INT ( ( ROW - BAND - ( STATION - 1 ) * 8 ) / 2 ) + 1
```

In fig. 3 is reported the flow chart of the program, whose main steps are described below.

- 1) ASK INFORMATION FOR INPUT/OUTPUT
tape logical unit number

number of records to analyse
initial and final day and year
etc.

2) READ A RECORD I4 (160, 15)

3, 4) SEARCH FOR FIRST RELEVANT DATA

5, 6, 7) ANALYSE DATA AND FILL THE LIST

8) OUTPUT OPERATIONS

if the list (i. e. the output buffer) of the required day is empty, (if there are no data, for example) the program prints a warning, otherwise it prints the required list.

10) START ANALYSIS OF A NEW REQUIRED DAY (if any)

11) STOP

PLOTREGRESS

This program provides plots of STANDARD data for each day and mode.

DATA STRUCTURE

The input data are the STANDARD file generated by the program DECODEREGRESS. The user selects the passes to be plotted for each desired day. DOY, mode and the DSS are required as input parameters. The data appear into three curves (S-band, X-band and S-3/11*X) as shown in fig. 4.

ALGORITHM

The program flow chart is shown in fig. 5.

- 1) ASK INFORMATION FOR INPUT/OUTPUT
 - 1a) options and parameters for the job as:
 - initial and final REGRES records
 - tape logical unit number
 - required days and modes
 - etc.
 - 1b) search for the initial record to analyse
- 2) REWIND TAPE
- 3) READ A RECORD
- 4) CHECK FOR DAY AND MODE
 - if data refers to the required day and mode, they are stored in a buffer
- 5) DO DATA REFER TO A LATER DAY?
 - in this case the selected data are plotted
- 6) LAST RECORD?
 - the search for the relevant data is repeated for

all records;
the search ends if the data of a record refer to a
later day;
if there are no data to plot, the program prints a
warning and goes to step #8.

7) PLOTTING

this step is carried out by a software package
developped at IFSI

8) OTHER PLOTS?

in this case, steps (1-7) are repeated.

9) STOP

FFREGRES

This program stores S and X band Doppler residuals and oscillator frequency from STANDARD tapes into disk files. Each file contains data referring to a given pass. Besides Doppler residuals, each file contains a header which reports spacecraft angular data, RTLT and other information. Some of these quantities are retrieved from the file DATA(FILE#1 (see Iess and Armstrong, 1985)

DATA STRUCTURE

INPUT : The input data are the STANDARD data and angular data FILE#1 (see Tab. 8)

OUTPUT: In output one obtains ASCII disk files relative to a single pass

BUFFER DIMENSION: ISTORE(3, 730)

RECORD LENGTH: 2190 double integers, i.e. 4380
16-bit word

RECORD FORMAT: each of the 3 rows contains 730 double integers. The file name has the following mnemonic code:

DAT/RODTTRRDDD

where:

DAT is the data subdirectory;
ROD stands for REGRES Original Doppler resid. ;
TT is the code for transmitting DSS;
RR is the code for receiving DSS;
DDD are three characters indicating the DOY.

DATA FORMAT: each file (see tab. 9) is composed by a header, with general information about the pass, followed by S and X band residuals and oscillator frequency in the first, second and third row respectively. Residuals are given in mmHz while

the oscillator frequency is given in Hz. The header contains initial and final time, number of data, receiving and transmitting DSS, tracking mode, RTLT, spacecraft's right ascension and declination at the middle of the pass. An example of residual file is reported in tab. 10.

ALGORITHM

The algorithm looks for data referring to the required receiving DSS, mode and begin of tracking day. Then it selects data from FILE#1 to build the header (see fig. 6).

For the Voyager I data the sampling rate was of 1 pt/min: therefore each Doppler residual refers to a given minute of the day (MOD). The time T (in MOD) of every datum can be obtained from the following relation:

$$T = \text{module} (I - ii - T_{in}, 1440)$$

where I is the column number of the datum in the array ISTORE, and T_{in} the MOD of the first datum of the file. Since the header must be skipped, ii must be subtracted from I to get the right position. Finally, the remainder of the division of $I - ii - T_{in}$ by 1440 provides the MOD of the datum (if $I - ii - T_{in} > 1440$, the MOD refers to the next day).

ACKNOWLEDGEMENTS

We are grateful to B. Bertotti (P. I. of the Ulysses GWE) for his help in the preparation of this report. Special thanks are also due to J. Brenkle, and A. Khatib for their cooperation during the stay one of us (L. Iess) at JPL, in the summer 1985. We thank also M. Stazi for the preparation of the figures.

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APPENDIX A

LIST OF ACRONYMS AND NAMES

ATDF	Archival Tracking Data File
DOY	Day Of the Year
DSN	Deep Space Network
DSS	Deep Space Station
EOF	End Of File
GIN	Generalised INput file
GWE	Gravitational Wave Experiment
IDR	Intermediate Data Records
MOD	Minute Of the Day
ODP	Orbit Determination Program
PET	Probe Ephemeris Tape
PV	Path-Vary
REGRES	Regression files
RTLT	Round Trip Light Time

APPENDIX B

PROGRAM LISTINGS

We report in this appendix the fortran program listings of the computer programs used in the data analysis.

```

C PROGRAM UNIHP
C ****
C * TRASFORMAZIONE DEI NASTRI REGRESS IN FORMATO UNIVAC *
C ****
C *
C * QUESTO PROGRAMMA OPERA SUI DATI REGRESS *
C *
C ****
C DICHIARAZIONI
COMMON /DATI/A(801),AOUT(100),NROUT
DOUBLE PRECISION ARRAY(20,40),A
CHARACTER*80 AOUT
C
IOUT=10
IOUT2=11
PRINT 1
1 FORMAT(2X,'N. RECORD INITIAL AND FINAL?')
READ(5,*) NIN,NFI
NRIN=NFI-NIN+1
PRINT 2
2 FORMAT(2X,' DOYOU WANT PRINTOUT OF A(20,40)? <1=SI>')
READ(5,*) ISTM
NR=0
NROUT=0
LL=0
N1=NIN-1
IF(N1.EQ.0) GO TO 100
200 CONTINUE
CALL NTRAN$(IOUT,2,1600,ARRAY,L,22)
NR=NR+1
IF(L.LT.0) GO TO 500
IF(NR.LT.N1) GO TO 200
100 CONTINUE
CALL NTRAN$(IOUT,2,1600,ARRAY,L,22)
NR=NR+1
IF(L.LT.0) GO TO 500
IF(L.EQ.-2) GO TO 610
IF(ISTAM.NE.1) GO TO 150
WRITE(8,300) NR
WRITE(8,400)
WRITE(8,700) (ARRAY(L,1),L=1,20)
WRITE(8,400)
WRITE(8,700) (ARRAY(L,40),L=1,20)
WRITE(8,400)
150 CONTINUE
A(801)=0.00
II=0
DO 10 I=1,40
DO 10 J=1,20
II=II+1
A(II)=ARRAY(J,I)

```

```

10  CONTINUE
    DO 20 L=1,801,3
    L1=L+2
    CALL FILBUF(LL,IOUT2)
    ENCODE(80,800,AOUT(LL),JJ,ERR=900) NR,LL,(A(K),K=L,L1)
    IF(ISTAM.NE.1) GO TO 20
    IF(L1.GT.9.AND.L1.LT.793) GO TO 20
    WRITE(8,850) LL,AOUT(LL)
850  FORMAT(2X,'LL=',I3,2X,A80)
20  CONTINUE
800  FORMAT(I5,I3,3D24.18)
950  FORMAT(2X,'ERROR WRITE K,LL,NR,NROUT',4I9)
C
        IF(NR.GT.NFI) GO TO 600
        GO TO 100
C
300  FORMAT(2X,'RECORD NUMBER =',I10)
400  FORMAT(//)
700  FORMAT(2X,3D24.18)
C
500  CONTINUE
PRINT 3,NR,NROUT
3   FORMAT(2X,'HARDWARE ERROR, NR,L NROUT',2X,3I9)
STOP
610  CONTINUE
PRINT 6,NR,NROUT
6   FORMAT(2X,'EOF AFTER N. RECORDS =',I10,2X,' NROUT = ',I10)
600  CONTINUE
C
        CALL NTRAN$(IOUT2,1,2000,AOUT,L,22)
        NROUT=NROUT+1
        PRINT 5,NROUT,NRIN
        WRITE(8,400)
        WRITE(8,5) NROUT,NRIN
5   FORMAT(2X,'NUMBER OF RECORDS WRITTEN AND READ',2X,2I10)
        CALL NTRAN$(IOUT2,9,2000,AOUT,L,22)
        GO TO 1000
900  PRINT 950,K,LL,NR,NROUT
1000 CONTINUE
C
C FINE DEL MAIN
    STOP
    END
C
C ****
C QUESTA SUBROUTINE RIEMPIE IL BUFFER
    SUBROUTINE FILBUF(LL,IOUT2)
C
    COMMON /DATI/A(801),AOUT(100),NROUT
    CHARACTER*80 AOUT
    DOUBLE PRECISION A
C
    LL=LL+1

```

```
IF(LL.LT.100) RETURN
CALL NTRAN$(IOUT2,1,2000,AOUT,L,22)
IF(L.LT.0) PRINT 10,NROUT
NROUT=NROUT+1
NO=(NROUT/50)*50-NROUT
IF(NO.EQ.0) PRINT 20,NROUT
10 FORMAT(2X,'HARDWARE ERROR AT RECORD =',I10)
20 FORMAT(2X,'NUMBER OF RECORDS WRITTEN =',I10)
LL=1
C
C RITORNO AL MAIN
RETURN
C
C FINE DI FILBUF
END
```



```

ENDIF
IF(IONLY.NE.1) THEN
  WRITE(1,'("VUOI IMMAGAZZINARE I DATI STANDARD? <1=SI>: ")')
  READ(1,*) IPRINT2
  IF(IPRINT2.EQ.1) THEN
    WRITE(1,'("UNITA'' NASTRO IN SCRITTURA?: ")')
    READ(1,*) ITAPE1
    IF(ITAPE.EQ.ITAPE1) THEN
      WRITE(1,*) 'ATTENTO! HAI FORNITO LA STESSA UNITA'' NASTRO'
      WRITE(1,*) 'SIA IN SCRITTURA CHE IN LETTURA!'
      GO TO 111
    ENDIF
  ENDIF
  WRITE(1,'("VUOI UNA STAMPA DEI DATI STANDARD? <1=SI>: ")')
  READ(1,*) IPRINT1
  IF(IPRINT1.EQ.1) THEN
    WRITE(1,'("UNITA'' STAMPANTE?: ")')
    READ(1,*) IWR1
    WRITE(IWR1,*)
  ENDIF
ENDIF

C RICERCA DEL RECORD INIZIALE RICHIESTO
NRC=NIN-1
IF(NRC.NE.0) WRITE(1,*) 'RICERCA DEL RECORD INIZIALE'
DO 1 I=1,NRC
  CALL XTAPE(1,ITAPE,ISK,4000,LEN)
  IF(LEN.NE.4000) THEN
    WRITE(1,100) I,LEN
  100 FORMAT(2X,'ERRORE IN LETTURA REC# ',I5,' LUN.# ',I5)
  ENDIF
  1 CONTINUE
  WRITE(1,200) NRC
  200 FORMAT('NUMERO DI RECORDS REGRESS SALTATI:',I5)
  WRITE(1,300)
  300 FORMAT(1X,/,/,80'*')

C PER CIASCUN RECORD RICHIESTO
DO 2 II=NIN,NFI
  IRC=IRC+1

C LETTURA DI UN RECORD
  CALL XTAPE(1,ITAPE,ISK,4000,LEN)
  IF(LEN.NE.4000) THEN
    IF(LEN.EQ.-1) THEN
      WRITE(1,*) 'EOF IN LETTURA'
      GO TO 10
    ENDIF
    WRITE(1,100) 'ERRORE IN LETTURA RECORD #',II,' LUN.=',LEN
    GO TO 2
  ENDIF
  WRITE(1,*) 'LETTO DALLA UNITA''',ITAPE,' IL RECORD #',II

```

```

C STAMPA IL RECORD REGRESS SE RICHIESTO
IF(IPRINT.EQ.1) THEN
  IF(IWR.NE.1) WRITE(1,*) 'SCRITTURA SULLA UNITA''',IWR,
  +' REC #',II
  WRITE(IWR,400) II
400  FORMAT(1X,'      RECORD # ',IS)
  WRITE(IWR,500) ((ISK(I,J),I=1,40),J=1,100)
500  FORMAT(40A2)
  WRITE(IWR,600)
600  FORMAT()
  IF(IONLY.EQ.1) GO TO 2
ENDIF

C
C PER CIASCUNA COLONNA DEL RECORD
DO 3 ICL=1,100
C
C CONTROLLO SUGLI IDENTIFICATORI
CALL SMOVE(ISK(1,ICL),1,8,IA,1)
DECODE(8,700,IA,ERR=20) IC1,IC3
700  FORMAT(IS,13)
  IF(IC1.NE.IC2) THEN
    IC2=IC1
    IP=1
  ENDIF

C
C TRANSFERIMENTO DI UNA COLONNA DI 'ISK' IN 'ISK1' CONTROLLANDO,
C DATO PER DATO, SE IL BUFFER E' PIENO (TEST SU IP)
CALL SMOVE(ISK(1,ICL),9,32,ISK1(1),IP)
CALL CONTROLLO(LMAT)
CALL SMOVE(ISK(1,ICL),33,56,ISK1(1),IP)
CALL CONTROLLO(LMAT)
CALL SMOVE(ISK(1,ICL),57,80,ISK1(1),IP)
CALL CONTROLLO(LMAT)

C
C SI RIPETE PER UN' ALTRA COLONNA
3  CONTINUE

C
C SI RIPETE PER UN ALTRO RECORD
2  CONTINUE

C
C OPERAZIONI FINALI
10 REWIND ITAPE
  IF(IONLY.NE.1) THEN

C
C SI IMMAGAZZINANO I DATI RIMASTI IN MEMORIA
  IF(IPRINT2.EQ.1) THEN
    ILM2=ILM2+1
    CALL XTAPE(2,ITAPE1,LMAT,4800,LEN)
    IF(LEN.NE.4800) THEN
      WRITE(1,*) 'ERRORE IN SCRITTURA SU ',ITAPE1
      WRITE(1,*) 'LMAT #',ILM2,' LEN =',LEN
    ENDIF
    WRITE(1,*) '**SCRITTO SU',ITAPE1,' #',ILM2,' RECORDS STANDARD'
  ENDIF

```

```

ENDIF
IF(IPRINT1.EQ.1) THEN
  ILM1=ILM1+1
  WRITE(1,*) 'SCRITTURA SU',IWR1,' DEL RECORD #',ILM1
  DO 4 MM=1,160
  4   WRITE(IWR1,800) MM,(LMAT(MM,NN),NN=1,15)
  800  FORMAT(I3,I6,I7,I9,I7,I9,I8,I9,I6,I7,I8,517)
ENDIF

C SCRITTURA DELL' EOF SUL NASTRO IN USCITA
IF(IPRINT2.EQ.1) THEN
  WRITE(1,'("VUOI UN ALTRO NASTRO REGRESS? (1=SI): "))')
  READ(1,*) NY
  IF(NY.EQ.1) GO TO 111
  ENDFILE(UNIT=ITAPE1,IOSTAT=KKK,ERR=30)
  WRITE(1,*) '**SCRITTO EOF SU',ITAPE1
  REWIND ITAPE1
ENDIF
ENDIF

C FINE REGOLARE DELL' ANALISI
WRITE(1,300)
WRITE(1,*) '*****'
WRITE(1,*) '**LETTI DA',ITAPE,' ',NFI-NIN+1,' R. RECORDS'
IF(IPRINT.EQ.1) THEN
  WRITE(1,*) '*****'
  WRITE(1,*) 'SCRITTI SU',IWR,' ',IRC,' R. RECORDS'
ENDIF
IF(IPRINT2.EQ.1) THEN
  WRITE(1,*) '*****'
  WRITE(1,*) 'IMMAGAZZINATI SU',ITAPE1,' ',ILM2,' S. RECORDS'
ENDIF
IF(IPRINT1.EQ.1) THEN
  WRITE(1,*) '*****'
  WRITE(1,*) 'SCRITTI SU',IWR1,' ',ILM1,' S. RECORDS'
ENDIF
WRITE(1,*) '*****'
WRITE(6,300)
WRITE(6,*) '*****'
WRITE(6,*) '**LETTI DA',ITAPE,' ',NFI-NIN+1,' R. RECORDS'
IF(IPRINT.EQ.1) THEN
  WRITE(6,*) '*****'
  WRITE(6,*) 'SCRITTI SU',IWR,' ',IRC,' R. RECORDS'
ENDIF
IF(IPRINT2.EQ.1) THEN
  WRITE(6,*) '*****'
  WRITE(6,*) 'IMMAGAZZINATI SU',ITAPE1,' ',ILM2,' S. RECORDS'
ENDIF
IF(IPRINT1.EQ.1) THEN
  WRITE(6,*) '*****'
  WRITE(6,*) 'SCRITTI SU',IWR1,' ',ILM1,' S. RECORDS'
ENDIF
WRITE(6,*) '*****'

```

```

      WRITE(1,900)
900 FORMAT(1X,/,50'*','FINE REGOLARE DELL''ANALISI')
      REWIND ITAPE
      REWIND ITAPE1
      STOP
C
C ERRORE DI DECODIFICA
20 WRITE(1,*) '**ERRORE DI DECODIFICA**'
      STOP
C
C ERRORE IN EOF
30 WRITE(1,*) 'ERRORE SU',ITAPE1,' IN EOF #',KKK
      STOP
C
C FINE DEL MAIN
      END
C
C ****
C QUESTA SUBROUTINE SLITTA L' INDICE DI POSIZIONE NEL BUFFER
C E LO DECODIFICA SE QUESTO E' PIENO
      SUBROUTINE CONTROLLO(LMAT)
C
C DICHIARAZIONI
      COMMON ISK1(240),IP,IRM,IRC,IC3,IPRINT1,IPRINT2,ITAPE1
      COMMON IWR1,NIN,ILM1,ILM2
      INTEGER*4 LMAT(160,15)
      INTEGER*4 LYD,LHMS,LTRM,LE,LB,LFRQ
      DOUBLE PRECISION DTIM,DOBS,DFRQ,DPAS,DCOM,DRTL,DHRG,DDEC,DAZM
      DOUBLE PRECISION DELV,DG1,DGM3,DGM1,DRES,DRJC,DWGH,DCRS,DMOD
      CHARACTER A1,A2,A3,A4,A(10)
C
C SLITTAMENTO DELL' INDICE DI POSIZIONE NEL BUFFER
      IP=IP+24
C
C CONTROLLO SUL RIEMPIIMENTO DEL BUFFER
      IF(IP.EQ.481) THEN
C
C IL BUFFER E' PIENO: CONTIENE TUTTI I DATI RELATIVI AD UNA MISURA
C SI EFFETTUO LA DECODIFICA
      IP=1
      DECODE(480,100,ISK1,ERR=900) DTIM,A1,LYD,LHMS,(A(K),K=1,10),
      +IB,IT,IR,IM,A2,A3,A4,DOBS,DFRQ,DPAS,DCOM,DRTL,DHRG,DDEC,DAZM,
      +DELV,DG1,DGM3,DGM1,DRES,DRJC,DWGH,DCRS,DMOD
      100 FORMAT(D24.18,A2,I5,I7,10A2,4I2,3A2,17D24.18)
C
C CONTROLLO SULLA BONTA' DEI DATI
      IF(DRJC.NE.0.D0.DR.DWGH.NE.0.D0) THEN
          ICO=IRC+NIN-1
          WRITE(1,*) ' RECORD #',ICO,IC3
          WRITE(1,*) ' ERRORE NEI DATI: REJCOD =',DRJC,' WEIGHT =',DWGH
          WRITE(1,*) ' -----'
      ENDIF
C

```

```

C ELABORAZIONE DEI DATI
    LHMS=LHMS/10.
    LTRM=IT*10000.+IR*100.+IM
    CALL ELEV(IT,DHRG,BDEC,EL)
    IELUP=DG1*100.
    IELDW=EL*100.
    LE=IELUP*10000.+IELDW
    LB=DRES*1000000.
    LFREQ=BFRQ

C TRASFERIMENTO DEI DATI NEL BUFFER DI USCITA
    IF(LMAT(IRM,1).EQ.LYD.AND.LMAT(IRM,2).EQ.LHMS.AND.LMAT(IRM,3)
    + .EQ.LFREQ.AND.LMAT(IRM,4).EQ.I.TRM.AND.LMAT(IRM,5).EQ.LE) THEN
C MISURA CONTEMPORANEA ALLA PRECEDENTE
    IF(IB.EQ.11) THEN
C S-BAND
        LMAT(IRM,6)=LB
        LMAT(IRM,9)=DRES
        ELSE
C X-BAND
        LMAT(IRM,7)=LB
        LMAT(IRM,10)=DRES
        IF(IB.NE.21) THEN
            LMAT(IRM,12)=99999999
            ELSE
                TBD=LMAT(IRM,6)-3./11.*LMAT(IRM,7)
                LMAT(IRM,8)=TBD
            ENDIF
        ENDIF
    ELSE
C TRASFERIMENTO IN UNA NUOVA RIGA DEL BUFFER LMAT
        IRM=IRM+1
C CONTROLLO SUL RIEMPIMENTO DEL BUFFER DI USCITA
        IF(IRM.EQ.161) THEN
            IF(IPRINT2.EQ.1) THEN
                ILM2=ILM2+1
                CALL XTape(2,ITAPE1,LMAT,4800,LEN)
                IF(LEN.NE.4800) THEN
                    WRITE(1,*) 'ERRORE IN SCRITTURA SU',ITAPE1
                    WRITE(1,*) 'LMAT #',ILM2,' LUN =',LEN
                ENDIF
                WRITE(1,*) '**SCRITTO SU',ITAPE1,' S. RECORD #',ILM2
            ENDIF
            IF(IPRINT1.EQ.1) THEN
                ILM1=ILM1+1
                WRITE(1,*) 'SCRITTURA SU',IWR1,' S. RECORD #',ILM1
                DO 1 MM=1,160
1                   WRITE(IWR1,200) MM,(LMAT(MM,NN),NN=1,15)
200                  FORMAT(I3,I6,I7,I9,I7,I9,I8,I9,I6,I7,I8,SI7)
                ENDIF
                DO 2 MM=1,160

```

```

        DO 2 NN=1,15
2      LMAT(MM,NN)=0
      IRM=1
      ENDIF
C
C MISURA NON CONTEMPORANEA ALLA PRECEDENTE
      LMAT(IRM,1)=LYD
      LMAT(IRM,2)=LHMS
      LMAT(IRM,3)=DFRQ
      LMAT(IRM,4)=LTRM
      LMAT(IRM,5)=LE
      LMAT(IRM,11)=DRJC*10.***6
      LMAT(IRM,12)=DWGH*10.***6
      IF(IB.EQ.11) THEN
C S-BAND
      LMAT(IRM,6)=LB
      LMAT(IRM,9)=DOBS
      ELSE
C X-BAND
      LMAT(IRM,7)=LB
      LMAT(IRM,10)=DOBS
      ENDIF
      ENDIF
C
C RITORNO AL MAIN
      ENDIF
      RETURN
C
C ERRORE DI DECODIFICA DEL BUFFER
      900 WRITE(1,*) '**ERRORE DI DECODIFICA DEL RECORD**'
      STOP
C
C FINE DI CONTROLLO
      END
C
C ****
C QUESTA ROUTINE CALCOLA L' ELEVAZIONE
      SUBROUTINE ELEV(IT,DHRG,DDEC,EL)
C
C DICHIARAZIONI
      DOUBLE PRECISION DHRG,DDEC
C
C RICERCA DELLA LATITUDINE DELLA STAZIONE IN QUESTIONE
      IF(IT.EQ.12) THEN
          LATD=35
          LATP=17
          ELSE
      IF(IT.EQ.14) THEN
          LATD=35
          LATP=25
          ELSE
      IF(IT.EQ.42) THEN
          LATD=-35

```

```

LATP=24
      ELSE
IF(IT.EQ.43) THEN
LATD=-35
LATP=24
      ELSE
IF(IT.EQ.61) THEN
LATD=40
LATP=25
      ELSE
IF(IT.EQ.63) THEN
LATD=40
LATP=25
ENDIF
ENDIF
ENDIF
ENDIF
ENDIF
ENDIF

C CALCOLA L' ELEVAZIONE
PIG=3.141592654
CON=PIG/180.
IF(LATD.GT.0) THEN
ALAT=CON*(LATD+LATP/60.)
ELSE
ALAT=CON*(LATD-LATP/60.)
ENDIF
RH RG=DH RG*CON
RDEC=DDEC*CON
SINEL=COS(RDEC)*COS(ALAT)*COS(RH RG)+SIN(RDEC)*SIN(ALAT)
EL=ASIN(SINEL)
EL=EL/CON

C RITORNO AL MAIN
RETURN
C
C FINE DI ELEV
END

```

```

FTN7X,S
C
C      PROGRAM STATREGRESS(),          (880329.1415)
C
C **** LISTA RIASSUNTIVA DEI DATI STANDARD ****
C * LISTA RIASSUNTIVA DEI DATI STANDARD *
C **** QUESTO PROGRAMMA OPERA SUI DATI STANDARD *
C *
C * ESSO PRODUCE IN USCITA UNA LISTA RIASSUNTIVA DEL NUMERO *
C * DI DATI STANDARD SEPARANDOLI, PER OGNI GIORNO DI DATI *
C * RICHIESTO, PER ORA, STAZIONE, BANDA E MODO DI COLLEGAMENTO *
C *
C **** DICHIARAZIONI ****
C
C      INTEGER*4 LMAT(160,15),IYD,ZERO
C      DIMENSION NATR(48,24)
C      CHARACTER B
C
C      INFORMAZIONI DI INGRESSO/USCITA
C      WRITE(1,100)
C 100 FORMAT(1X,20/,80'*')
C      WRITE(1,*) ' LISTA RIASSUNTIVA DEI DATI STANDARD'
C      WRITE(1,*) ' ****'
C      WRITE(1,*) ' QUESTO PROGRAMMA PRODUCE ITERATIVAMENTE, '
C      WRITE(1,*) ' PER OGNI GIORNO DI DATI STANDARD RICHIESTO, '
C      WRITE(1,*) ' UNA LISTA RIASSUNTIVA DEL NUMERO DI DATI '
C      WRITE(1,*) ' SEPARANDOLI PER ORA, STAZIONE, BANDA E MODO.'
C      WRITE(1,101)
C 101 FORMAT(1X,/,80'*',/)
C      10 WRITE(1,'("NASTRO DI LETTURA (ENTER 8 OR 9) #: ")')
C      READ(1,*) ITAPE
C      IF(ITAPE.NE.8.AND.ITAPE.NE.9) GO TO 10
C      REWIND ITAPE
C      30 WRITE(1,'("GIORNO INIZIALE (DA 1 TO 365): ")')
C      READ(1,*) IDAYI
C      IF(IDAYI.LE.0.OR.IDAYI.GE.366) GO TO 30
C      40 WRITE(1,'("GIORNO FINALE (DA 1 TO 365) #: ")')
C      READ(1,*) IDAYF
C      IF(IDAYF.LE.0.OR.IDAYF.GE.366) GO TO 40
C      50 WRITE(1,'("ANNO:19 ")')
C      READ(1,*) IYEAR
C      IF(IYEAR.GE.100) GO TO 50
C      WRITE(1,'("STAMPANTE #: ")')
C      READ(1,*) IWR
C      ZERO=0
C
C      PER CIASCUN GIORNO RICHIESTO
C      DO 8 ID=IDAYI, IDAYF

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```

IYD=IYEAR*1000.+ID
C
C INIZIALIZZAZIONE
NRC=0
DO 1 II=1,24
    DO 1 JJ=1,48
1  NATR(JJ,II)=0
    CALL EXEC(3,ITAPE+0200B)
    IPAGE=12
    WRITE(IWR,200) IPAGE
200  FORMAT(A2)
C
C LETTURA DI UN RECORD
2  CALL XTAPE(1,ITAPE,LMAT,4800,LEN)
    NRC=NRC+1
    IF(LEN.EQ.-1) THEN
        WRITE(1,*) 'EOF IN LETTURA'
        GO TO 60
    ENDIF
    IF(LEN.NE.4800) WRITE(1,*) '**ERRORE IN LETTURA: LUN.=',LEN
C
C PER CIASCUNA RIGA DEL RECORD
    DO 3 I=1,160
        IRG=I
C
C RICERCA DEL GIORNO RICHIESTO
    IGO=LMAT(I,1)-IYD
    IF(IGO.LT.0) GO TO 3
    IF(IGO.GT.0) GO TO 60
C
C ANALISI DEI DATI PER LA MTRICE
    IRM=LMAT(I,4)-LMAT(I,4)/10000*10000
    IR=IRM/100
    IM=IRM-IR*100-10
    IF(IR.EQ.12) THEN
        IRR=1
        ELSE
    IF(IR.EQ.14) THEN
        IRR=2
        ELSE
    IF(IR.EQ.42) THEN
        IRR=3
        ELSE
    IF(IR.EQ.43) THEN
        IRR=4
        ELSE
    IF(IR.EQ.61) THEN
        IRR=5
        ELSE
    IF(IR.EQ.63) IRR=6
    ENDIF
    ENDIF
    ENDIF

```

```

        ENDIF
    ENDIF
    IH=LMAT(I,2)/10000
    IMS=LMAT(I,2)-IH*10000
    IBT=IH*60+IMS/100+1
C
C RIEMPIMENTO DELLA LISTA
    I2=(IBT-1)/60.+1
    IB=1
    I1=(IRR-1)*8+(IM-1)*2+IB
    IF(LMAT(I,6).NE.ZERO) NATR(I1,I2)=NATR(I1,I2)+1
    IB=2
    I1=(IRR-1)*8+(IM-1)*2+IB
    IF(LMAT(I,7).NE.ZERO) NATR(I1,I2)=NATR(I1,I2)+1
C
C SI RIPETE PER UN'ALTRA RIGA
    3 CONTINUE
C
C SI RIPETE PER UN ALTRO RECORD
    GO TO 2
C
C FINE DELLA RICERCA DEI DATI
    60 IYEAR1=LMAT(IRG,1)/1000.
    IDAY1=LMAT(IRG,1)-IYEAR1*1000.
    WRITE(1,*) 'FINE RICERCA IL',IDAY1,' DELL'' ANNO ',IYEAR1
C
C SCRITTURA DELLA MATRICE DI USCITA
    DO 4 JJ=1,48
        DO 4 II=1,24
            IF(NATR(JJ,II).NE.0) IPRINT1=1
    4 CONTINUE
    IF(IPRINT1.EQ.1) THEN
        IPRINT1=0
        WRITE(IWR,300)
300    FORMAT(2X,132'./.,/,/)
        WRITE(IWR,400) IYEAR, ID
400    FORMAT(2X,'YEAR = ',I3,5X,'DAY = ',I4,9X,'HOUR = 0 1 2 3 4'
*, ' 5 : 6 7 8 9 10 11 : 12 13 14 15 16 17 : 18'
*, ' 19 20 21 22 23 NS DAY',/,/)
        DO 7 JJ=1,48
            DO 5 II=1,24
    5 IF(NATR(JJ,II).NE.0) IPRINT=1
            IF(IPRINT.EQ.1) THEN
                IPRINT=0
                IS=(JJ-1)/8.+1
                IF(IS.EQ.1) THEN
                    ISS=12
                ELSE
                    IF(IS.EQ.2) THEN
                        ISS=14
                    ELSE
                        IF(IS.EQ.3) THEN
                            ISS=42

```

```

        ELSE
IF(IS.EQ.4) THEN
  ISS=43
        ELSE
IF(IS.EQ.5) THEN
  ISS=61
        ELSE
IF(IS.EQ.6) ISS=63
ENDIF
ENDIF
ENDIF
ENDIF
IP=JJ/2.
IF(IP*2.EQ..IJ) THEN
  B='X'
  IBB=2
        ELSE
  B='S'
  IBB=1
ENDIF
IMM=(JJ-IBB-(IS-1)*8)/2+1
ITOT=0
DO 6 LL=1,24
  ITOT=ITOT+NATR(JJ,LL)
  IF(IS1.NE.IS) WRITE(IWR,*)
  IS1=IS
  WRITE(IWR,500) ISS,B,IMM,(NATR(JJ,LL),LL=1,24),ITOT
500 FORMAT(2X,'DOP : DSS =',I3,' Band-Mode ',A1,I2,4X,6I3,
*,':',6I3,:',6I3,:',6I3,I8)
  ENDIF
6  CONTINUE
  WRITE(IWR,*)
  WRITE(IWR,300)
ENDIF

C SI RIPETE PER UN ALTRO GIORNO
IF(LEN.EQ.-1) GO TO 70
  8 CONTINUE

C FINE REGOLARE DELL' ANALISI
70 WRITE(IWR,200) IPAGE
  WRITE(IWR,200) IPAGE
  WRITE(1,*)
  WRITE(1,*) '**FINE REGOLARE DELL' ANALISI**'
  STOP

C FINE DEL MAIN
END

```

```
FTN7X,5
C
C      PROGRAM PLOTREGRESS(),          <880329.1415>
C
C ****
C * TRACCIAMENTO SEQUENZIALE DEI DATI STANDARD *
C ****
C * QUESTO PROGRAMMA OPERA SUL DATI STANDARD      *
C *
C * ESSO TRACCIA TUTTI I DATI RELATIVI AL GIORNO, ALLA STAZIONE ED   *
C * AL MODO RICHIESTO.                                *
C * QUESTI VENGONO TRACCIATI SEPARATI PER BANDA IN TRE GRAFICI    *
C * NEL MASSIMO FORMATO.                                *
C *
C ****
C
C DICHIARAZIONI
      EMA BS(720), BX(720), BD(720), BT(720)
      INTEGER*4 LMAT(160,15), IYD
      DIMENSION V(29), IST(6), IMODE(4)
      CHARACTER*50 N1, N2
      INTEGER YNE
      CHARACTER*2 ANNO
C
C ESEGUIBILE
C INFORMAZIONI PER INGRESSO/USCITA
      WRITE(1,100)
100 FORMAT(1X,20',80'*',/)
      WRITE(1,*) ' TRACCIAMENTO SEQUENZIALE DEI DATI STANDARD'
      WRITE(1,*) ' ****'
      WRITE(1,*) '
      WRITE(1,*) '
      WRITE(1,*) ' QUESTO PROGRAMMA TRACCIA TUTTI I DATI'
      WRITE(1,*) ' RELATIVI A CIASCUN GIORNO RICHIESTO'
      WRITE(1,*) ' IN SUCCESSIONE PER STAZIONI E MODI'
      WRITE(1,*) '
      WRITE(1,*) ' I GRAFICI SONO 3 PER OGNI FOGLIO'
      WRITE(1,*) ' IL FORMATO E'' IL MASSIMO'
      WRITE(1,*) '
      WRITE(1,*) '
      WRITE(1,*) ' PENNINI DEL PLOTTER:'
      WRITE(1,*) ' 1: PER LE INTESTAZIONI'
      WRITE(1,*) ' 2: COMPLESSO 10'
      WRITE(1,*) ' 3: COMPLESSO 40'
      WRITE(1,*) ' 4: COMPLESSO 60'
      WRITE(1,*) '
      WRITE(1,101)
101 FORMAT(1X,/,80'*',/)
10  WRITE(1,'("NASTRO DI LETTURA (8 0 9) #: ")')
     READ(1,*) ITAPE
     IF(ITAPE.NE.8.AND.ITAPE.NE.9) GO TO 10
     REWIND ITAPE
```

```

30 WRITE(1,'("GIORNO INIZIALE (DA 1 A 365) #: ")')
    READ(1,*) IDAYI
    IF(IDAYI.LE.0.OR.IDAYI.GE.366) GO TO 30
40 WRITE(1,'("GIORNO FINALE (DA 1 A 365) #: ")')
    READ(1,*) IDAYF
    IF(IDAYF.LE.0.OR.IDAYF.GE.366) GO TO 40
50 WRITE(1,'("ANNO: 19 ")')
    READ(1,*) IYEAR
    IF(IYEAR.GE.100) GO TO 50
    WRITE(ANNO,102) IYEAR
102 FORMAT(I2)
    WRITE(1,'("VUOI L' ECO SULLA 6? <Y=1>: ")')
    READ(1,*) YN6
    IF(YN6.EQ.1) THEN
        IPAGE=12
        WRITE(6,200) IPAGE
200 FORMAT(A2)
    ENDIF
    NR=0
    NM=0
    DO I=1,6
        NR=NR+1
        WRITE(1,*) '***** 0 PER TERMINARE'
        WRITE(1,'("STAZIONE RICEVENTE? <12,14,42,43,61,63>: ")')
        READ(1,*) IST(NR)
        IF(IST(NR).EQ.0) THEN
            NR=NR-1
            GO TO 60
        ENDIF
        IF(IST(NR).NE.12.AND.IST(NR).NE.14.AND.IST(NR).NE.42.AND.
+IST(NR).NE.43.AND.IST(NR).NE.61.AND.IST(NR).NE.63) THEN
            NR=NR-1
            WRITE(1,*) '*****STAZIONE NON RICONOSCIUTA!*****'
            ENDIF
    END DO
60 DO I=1,4
    NM=NM+1
    WRITE(1,*) '***** 0 PER TERMINARE'
    WRITE(1,'("MODO RICHIESTO? <DA 1 A 4>: ")')
    READ(1,*) IMODE(NM)
    IF(IMODE(NM).EQ.0) THEN
        NM=NM-1
        GO TO 70
    ENDIF
    IF(IMODE(NM).LT.1.OR.IMODE(NM).GT.4) THEN
        NM=NM-1
        WRITE(1,*) '*****MODO NON RICONOSCIUTO!*****'
        ENDIF
    END DO
70 CONTINUE

```

```

C PER CIASCUN GIORNO RICHIESTO
DO 7 ID=IDAYI, IDAYF
    IYD=IYEAR*1000.+ID

C
C PER CIASCUN MODO RICHIESTO
DO 5 IMM=1,NM
    IM=IMODE(IMM)

C
C PER CIASCUNA STAZIONE RICHIESTA
DO 6 K=1,NR
    IS=IST(K)

C INIZIALIZZAZIONE
    IPO=0
    NRC=0
    DO 1 I=1,720
        BS(I)=0.
        BX(I)=0.
        BD(I)=0.
        BT(I)=0.

1 CONTINUE
    IF(YN6.EQ.1) THEN
        WRITE(6,*)
        WRITE(6,*)
        WRITE(6,*) 'DOY =',ID,' ANNO =',IYEAR,' STAZIONE RIC.=',IS,
        +' MODO =',IM
        WRITE(6,*)
        WRITE(6,*) 'MINUTO S-BAND X-BAND NON RIPORTATE'
        ENDIF
        WRITE(1,*) 'DOY =',ID,' ANNO =',IYEAR,' STAZIONE RIC.=',IS,
        +' MODO =',IM
        REWIND ITAPE

C LEGGE UN RECORD
2 CALL XTAPE(1,ITAPE,LMAT,4800,LEN)
    NRC=NRC+1
    IF(LEN.NE.4800) THEN
        IF(LEN.EQ.-1) THEN
            WRITE(1,*) '**EOF SU NASTRO',ITAPE
            GO TO 4
        ELSE
            WRITE(1,*) '**ERRORE IN LETTURA: LUN=',LEN,' SU ',ITAPE
        END IF
    END IF

C PER TUTTE LE RIGHE DEL BUFFER
DO 3 I=1,160
    IRG=I

C RICERCA DEL GIORNO RICHIESTO
    IGO=LMAT(I,1)-IYD
    IF(IGO.LT.0) GO TO 3
    IF(IGO.GT.0) GO TO 4

```

```

C
C CONTROLLO DEL MODO E DELLA STAZIONE
    IRM=LMAT(I,4)-LMAT(I,4)/10000*10000
    IR=IRM/100
    IM1=IRM-IR*100-10
C
C SE IL DATO E' QUELLO CERCATO
    IF(IM.EQ.IM1.AND.IS.EQ.IR) THEN
C
C IMMAGAZZINAMENTO DEL DATO PER LA GRAFICA
    IPO=IPO+1
    BS(IPO)=LMAT(I,5)/1000000.
    IF(BS(IPO).GT..5) BS(IPO)=.5
    IF(BS(IPO).LT.-.5) BS(IPO)=-.5
    BX(IPO)=LMAT(I,7)/1000000.
    IF(BX(IPO).LT.-2.5) BX(IPO)=-2.5
    IF(BX(IPO).GT.2.5) BX(IPO)=2.5
    BD(IPO)=LMAT(I,8)/1000.
    IF(BD(IPO).GT.20) BD(IPO)=20
    IF(BD(IPO).LT.-20) BD(IPO)=-20
    IH=LMAT(I,2)/10000
    IMS=LMAT(I,2)-IH*10000
    BT(IPO)=IH*60+IMS/100+1
    IF((BS(IPO).EQ.0.OR.BX(IPO).EQ.0).AND.YN6.EQ.1) THEN
        WRITE(6,300) BT(IPO),LMAT(I,6),LMAT(I,7)
300    FORMAT(2X,F5.0,I11,I11)
    IPO=IPO-1
    ENDIF
    ENDIF
C
C SI RIPETE PER UN' ALTERA RIGA
    3 CONTINUE
C
C SI RIPETE PER UN ALTRO RECORD
    GO TO 2
C
C FINE RICERCA DEI DATI
    4 IYEAR1=LMAT(IRG,1)/1000.
    IDAY1=LMAT(IRG,1)-IYEAR1*1000
    WRITE(1,*) 'FINE RICERCA IL:',IDAY1,' DELL'' ANNO',IYEAR1
C
C IN ASSENZA DI DATI NON SI TRACCIA IL GRAFICO
    IF(BT(1).EQ.0) THEN
        WRITE(1,*) '**NON CI SONO DATI PER QUESTO INGRESSO**'
        IF(YN6.NE.1) GO TO 6
        WRITE(6,*) '**NON CI SONO DATI DA GRAFICARE PER QUESTO INPUT**'
        GO TO 6
        ELSE
        WRITE(1,*) '**GRAFICI IN USCITA:',IPO,' PUNTI**'
        IF(YN6.EQ.1) THEN
            WRITE(6,*) '**GRAFICI IN USCITA:',IPO,' PUNTI'
        ENDIF
    ENDIF

```

```
C
C TRACCIAMENTO GRAFICI
V(1)=0
V(2)=-.5
V(3)=.5
V(4)=0
V(5)=0
V(6)=1440
V(7)=50
V(8)=30
V(9)=350
V(10)=90
V(11)=2
V(12)=3
V(13)=60.
V(14)=.02
V(15)=4
V(16)=5
V(17)=1
V(18)=0
V(19)=0
V(20)=0
V(21)=0
V(22)=1
V(23)=3
V(24)=4
IF(I5.EQ.12.OR.I5.EQ.14) V(25)=2
IF(I5.EQ.42.OR.I5.EQ.43) V(25)=3
IF(I5.EQ.61.OR.I5.EQ.63) V(25)=4
V(26)=1
V(27)=1
V(28)=0
V(29)=1
WRITE(1,*) 'TRACCIAMENTO PRIMO GRAFICO'
CALL SETPAR(V,N1,N2)
CALL EGRAPHY(BT,B5,IPO,1.,0,1)
WRITE(1,*) 'TRACCIATO PRIMO GRAFICO'
N2=' '
N1=' X-BAND [Hz]'
V(2)=-2.5
V(3)=2.5
V(8)=100
V(10)=160
V(14)=.1
WRITE(1,*) 'TRACCIAMENTO SECONDO GRAFICO'
CALL SETPAR(V,N1,N2)
CALL EGRAPHY(BT,BX,IPO,1.,0,1)
WRITE(1,*) 'TRACCIATO SECONDO GRAFICO'
N2=' '
N1='S-3/11*X [mHz]'
V(2)=-20.
V(3)=20.
V(8)=170
```

```

V(10)=230
V(14)=1
WRITE(1,*) 'TRACCIAMENTO TERZO GRAFICO'
CALL SETPAR(V,N1,N2)
CALL EGRAPHY(BT,BD,IPO,1.,0,1)
WRITE(1,*) 'TRACCIATO TERZO GRAFICO'

C
C SI RIPETE PER UN' ALTRA STAZIONE
    IF(YN6.EQ.1) WRITE(6,200) IPAGE
    6 CONTINUE

C
C COMPLETAMENTO DEL GRAFICO
    N2='   VOYAGER      19' //ANNO//'          REGRESS FILES'
    N1='   S-BAND [Hz]''
    V(1)=0
    V(2)=-.5
    V(3)=.5
    V(4)=0
    V(5)=0
    V(6)=1440
    V(7)=50
    V(8)=30
    V(9)=350
    V(10)=90
    V(11)=2
    V(12)=3
    V(13)=60.
    V(14)=.02
    V(15)=4
    V(16)=5
    V(17)=1
    V(18)=0
    V(19)=1
    V(20)=0
    V(21)=1
    V(22)=1
    V(23)=3
    V(24)=4
    V(25)=0
    V(26)=1
    V(27)=1
    V(28)=0
    V(29)=1
    WRITE(1,*) 'COMPLETAMENTO DEL GRAFICO'
    CALL SETPAR(V,N1,N2)
    CALL EGRAPHY(BT,BS,IPO,1.,0,1)
    N2=' '
    N1='   X-BAND [Hz]''
    V(2)=-2.5
    V(3)=2.5
    V(8)=100
    V(10)=160
    V(14)=.1

```

```

CALL SETPAR(V,N1,N2)
CALL EGRAPHY(BT,BX,IPO,1.,0,1)
N2=' '
N1='S-3/11*X [mHz]'
V(2)=-20.
V(3)=20.
V(8)=170
V(10)=230
V(14)=1
CALL SETPAR(V,N1,N2)
CALL EGRAPHY(BT,BD,IPO,1.,0,1)
CALL ZDLIM(0.,370.,0.,280.,IERR)
IF(IERR.NE.0) WRITE(1,*) 'ZDLIM ERROR #',IERR
CALL ZASPK(370.,280.)
CALL ZVIEW(0.,370.,0.,280.)
CALL ZWIND(0.,370.,0.,280.)
CALL ZCOLR(1)
CALL SYMBOL(43.,25.,-2.,'00.00',0.,5)
CALL SYMBOL(93.,25.,-2.,'04.00',0.,5)
CALL SYMBOL(143.,25.,-2.,'08.00',0.,5)
CALL SYMBOL(193.,25.,-2.,'12.00',0.,5)
CALL SYMBOL(243.,25.,-2.,'16.00',0.,5)
CALL SYMBOL(293.,25.,-2.,'20.00',0.,5)
CALL SYMBOL(343.,25.,-2.,'24.00',0.,5)
CALL SYMBOL(38.,30.,-2.,'-5',0.,3)
CALL SYMBOL(35.,100.,-2.,'-2.5',0.,4)
CALL SYMBOL(38.,170.,-2.,'-20.',0.,4)
FDAY=FLOAT(ID)
FDSS=FLOAT(IS)
FMOD=FLOAT(IM)
CALL SYMBOL(70.,260.,-3.,'DAY =',0.,5)
CALL NUMBER(95.,260.,-4.,FDAY,0.,3,'(I3)')
IF(NR.EQ.1) THEN
  CALL NUMBER(155.,260.,-4.,FDSS,0.,2,'(I2)')
  CALL SYMBOL(130.,260.,-3.,'DSS =',0.,5)
ENDIF
CALL SYMBOL(190.,260.,-3.,'MODE =',0.,6)
CALL NUMBER(220.,260.,-4.,FMOD,0.,1,'(I1)')
CALL ZNEWF
C
C SI RIPETE PER UN ALTRO MODO
  5 CONTINUE
C
C SI RIPETE PER UN ALTRO GIORNO
  7 CONTINUE
C
C DISATTIVAZIONE DEL PLOTTER
  CALL ZDEND
  CALL ZEND
C
C FINE REGOLARE DELL' ANALISI
  WRITE(1,*)
  WRITE(1,*) '**FINE REGULARE DELL'' ANALISI**'

```

REWIND ITAPE
STOP

C FINE DEL MAIN
END

```

FTN7X,S
$FILES(0,1)
C
    PROGRAM FFREGRESS(),           <880329.1415>
C
C **** C R E A Z I O N E D I D I S C F I L E S D E I D A T I S T A N D A R D ****
C * C R E A Z I O N E D I D I S C F I L E S D E I D A T I S T A N D A R D *
C **** Q U E S T O P R O G R A M M A O P E R A S U I D A T I S T A N D A R D *
C *
C *
C * E S S O C R E A D I S C F I L E S A P A R T I R E D A I D A T I I M M A G A Z Z I N A T I S U N A S T R O *
C * C I A S C U N F I L E C O N T I E N E D A T I R E L A T I V I A D U N S I N G O L O P A S S A G G I O *
C * A V E N D O C I O E ' F I S S A T O I L E S T A Z I O N I A T T I V E , I L M O D O E D I L G I O R N O *
C * D E L L ' I N I Z I O D E L P A S S A G G I O *
C * I L F I L E C O N T I E N E T U T T I I D A T I N E L L E B A N D E S E X E L A F R E Q U E N Z A *
C * D E L L ' O S C I L L A T O R E . *
C *
C * N . B . S I E ' A S S U N T O C H E F R A U N P A S S A G G I O E L ' A L T R O C I S I A N O 8 O R E *
C *
C **** D I C H I A R A Z I O N I ****
C D I C H I A R A Z I O N I
    INTEGER*4 LMAT(160,15),ISTORE(3,730),ANGDAT(120,6)
    INTEGER*4 IYEAR,IYD,ZERO
    DIMENSION IDSR(6),IDST(6),IMODE(4)
    CHARACTER*3 NY
    COMMON IPO,IPOS,IPOX,IAUTO,ISTORE,ANGDAT,LU
C
C E S E Q U I B I L E
C I N F O R M A Z I O N I D I I N G R E S S O / U S C I T A
    WRITE(1,100)
100 FORMAT(1X,20/,80'*',/)
        WRITE(1,*) '      C R E A Z I O N E D I D I S C F I L E S D E I D A T I S T A N D A R D '
        WRITE(1,*) ' ****'
        WRITE(1,*) '      Q U E S T O P R O G R A M M A C R E A D I S C F I L E S A P A R T I R E D A I '
        WRITE(1,*) '      N A S T R I S T A N D A R D . '
        WRITE(1,*) '      C I A S C U N F I L E C O N T I E N E D A T I R E L A T I V I A D U N S I N G O L O '
        WRITE(1,*) '      P A S S A G G I O N E L L E D U E B A N D E S E X E L A F R E Q U E N Z A '
        WRITE(1,*) '      D E L L ' ' O S C I L L A T O R E . '
        WRITE(1,200)
200 FORMAT(1X,/,80'*',/)
    10 WRITE(1,*) ' ***P A R A M E T R I P E R L ' ' A N A L I S I : '
        WRITE(1,'("N A S T R O I N L E T T U R A ( 8 0 9 ) # : "'))
        READ(1,*) ITAPE
        IF(ITAPE.NE.8.AND.ITAPE.NE.9) GO TO 10
        REWIND ITAPE
        WRITE(1,'("Q U A N T I R E C O R D S ? : "'))
        READ(1,*) NFI
        WRITE(1,'("V U O I L ' ' A N A L I S I A U T O M A T I C A ? ( 1 = S I ) : "'))

```

```

READ(1,*) IAUTO
WRITE(1,'("STAMPANTE #: ")')
READ(1,*) LU
IF(LU.NE.1) THEN
  WRITE(LU,300)
300 FORMAT(5X,'FILE NAMES',6X,'IN DAY   FIN DAY',6X,
+ 'YEAR    IN MIN   FIN MIN',6X,'MODE    TRS DSS   REC DSS',
+ 5X,'R ASC',7X,'DEC',6X,'RTLT')
  WRITE(LU,*)
ENDIF
20 WRITE(1,'("GIORNO INIZIALE? <DA 1 A 365>: ")')
  READ(1,*) IDAYI
  IF(IDAYI.LT.1.OR.IDAYI.GT.365) GO TO 20
30 WRITE(1,'("DELL' ANNO: 19 ")')
  READ(1,*) IYEAR
  IF(IYEAR.GT.99.OR.IYEAR.LT.1) GO TO 30
  ZERO=0
  NR=0
  NT=0
  NM=0
  DO 1 I=1,6
    NR=NR+1
    WRITE(1,*) '**** 0 PER TERMINARE'
    WRITE(1,'("STAZIONE RICEVENTE? <12,14,42,43,61,63>: ")')
    READ(1,*) IDSR(NR)
    IF(IDSR(NR).EQ.0) THEN
      NR=NR-1
      GO TO 40
    ENDIF
    IF(IDSR(NR).NE.12.AND.IDSR(NR).NE.14.AND.IDSR(NR).NE.42.AND.
+ IDSR(NR).NE.43.AND.IDSR(NR).NE.61.AND.IDSR(NR).NE.63) THEN
      NR=NR-1
      WRITE(1,*) '****STAZIONE NON RICONOSCIUTA!*****'
    ENDIF
1 CONTINUE
40 DO 2 I=1,4
  NM=NM+1
  WRITE(1,*) '**** 0 PER TERMINARE'
  WRITE(1,'("MODO? <DA 1 A 4>: ")')
  READ(1,*) IMODE(NM)
  IF(IMODE(NM).EQ.0) THEN
    NM=NM-1
    GO TO 50
  ENDIF
  IF(IMODE(NM).LT.1.OR.IMODE(NM).GT.4) THEN
    NM=NM-1
    WRITE(1,*) '****MODO NON RICONOSCIUTO!*****'
  ENDIF
2 CONTINUE
50 DO 1 I=1,6
  NT=NT+1

```

```

      WRITE(1,*) '**** 0 PER TERMINARE'
      WRITE(1,'("STAZIONE TRASMITTENTE? <12,14,42,43,61,63>: "'))'
      READ(1,*) IDST(NT)
      IF(IDST(NT).EQ.0) THEN
          NT=NT-1
          GO TO S1
      ENDIF
      IF(IDST(NT).NE.12.AND.IDST(NT).NE.14.AND.IDST(NT).NE.42.AND.
+IDST(NT).NE.43.AND.IDST(NT).NE.61.AND.IDST(NT).NE.63) THEN
          NT=NT-1
          WRITE(1,*)
          WRITE(1,*) '****STAZIONE NON RICONOSCIUTA'
      ENDIF
      END DO

C
C LEGGE I DATI ANGOLARI
S1  WRITE(1,*)
    WRITE(1,*) 'LETTURA FILE DAT/FILE#1'
    OPEN(70,FILE='DAT/FILE#1',IOSTAT=IOSO,STATUS='OLD',ERR=60)
    READ(70,*) ANGDAT
    CLOSE(70)
    GO TO 70
60  WRITE(1,*) 'ERRORE #',IOSO,' IN OPEN IL FILE DAT/FILE#1'
    WRITE(1,'(" VUOI ABORTIRE IL PROGRAMMA? (Y/N): "'))'
    READ(1,400) NY
400 FORMAT(A3)
    IF(NY.EQ.'Y'.OR.NY.EQ.'YES'.OR.NY.EQ.'1')
+STOP '***FINE IRREGOLARE DELL'' ANALISI***'
    GO TO 10

C
C SI FISSANO I PARAMETRI
70  DO 5 I1=1,NR
    IDSSR=IDSR(I1)
    IDSST=IDSSR
    I3=0
    DO 5 I2=1,NM
71   IMODES=IMODE(I2)
    IF(IMODES.GT.2) THEN
        I3=I3+1
        IF(I3.GT.NT) GO TO 5
        IDSST=IDST(I3)
        IF(IDSST.EQ.IDSSR) GO TO 71
    ENDIF
    WRITE(1,*)
    WRITE(1,*) 'RICERCA: MODO =',IMODES,' DSS RICEVENTE =',IDSSR,
+' DSS TRASMITTENTE =',IDSST

C
C INIZIALIZZAZIONE
    REWIND ITAPE
    IPO=0
    IPOS=0
    IPOX=0
    IBTF=0

```

```

IBTA=0
INIT=0
NEWDAY=0
IDAY=IDAYI
DO 3 II=1,3
  DO 3 JJ=1,730
    ISTORE(II,JJ)=0
  3  CONTINUE
  IYD=IYEAR*1000.+IDAY
  ITC=480

C
C LEGGE UN RECORD
  WRITE(1,*)
  WRITE(1,*) 'LEGGENDO DAL NASTRO', ITAPE
  NRC=0
1000  CALL XTAPE(1, ITAPE, LMAT, 4800, LEN)
  NRC=NRC+1
  IF(LEN.EQ.-1) GO TO 2000
  IF(LEN.NE.4800) WRITE(1,*) '**ERRORE IN LETTURA: LUN=', LEN, '**'

C
C PER CIASCUNA RIGA DEL BUFFER
  90  CONTINUE
    DO 4 I=1,160

C
C RICERCE DEL GIORNO RICHIESTO
  IGO=LMAT(I,1)-IYD
  IF(IGO.LT.0) GO TO 4
  IF(IGO.GT.0) THEN
    IDAY=IDAY+1
    IYD=IYD+1
    IF(INIT.EQ.0) GO TO 90
    NEWDAY=1
    IBTA=1440-IBTF
    ISTORE(2,9)=IBTF
    IBTF=0
  ENDIF

C
C ANALISI DEI DATI
  IST=LMAT(I,4)/10000
  IRM=LMAT(I,4)-IST*10000
  ISR=IRM/100
  IM=IRM-ISR*100-10
  IH=LMAT(I,2)/10000
  IMS=LMAT(I,2)-IH*10000
  IBT=IH*60+IMS/100

C
C FINE DEL PASSAGGIO
  IF((IBT-IBTF+IBTA).GT.ITC) THEN
    CALL CREA
    NEWDAY=0
    IBTF=IBT
    IBTA=0
  ENDIF

```

```

C
C DATO DA TRASFERIRE NEL BUFFER DI USCITA
    IF(ISR.EQ.IDSSR.AND.IM.EQ.IMODES.AND.IST.EQ.IDSST) THEN
        IPO=IPO+1
C
C PRIMO DATO PER IL BUFFER DI USCITA (RIEMPIMENTO DELLA TESTATA)
    IF(IPO.EQ.1) THEN
        IF(IAUTO.NE.1) THEN
            WRITE(1,*)
            WRITE(1,*) 'DATI PER QUESTO INPUT'
        ENDIF
        ISTORE(1,8)=IDAY
        ISTORE(1,9)=IDAY
        ISTORE(2,8)=IBT
        ISTORE(3,1)=2
        ISTORE(3,2)=IYEAR
        ISTORE(3,3)=IDSST
        ISTORE(3,4)=IDSSR
        ISTORE(3,5)=IMODES
        INIT=1
        NEWDAY=0
    ENDIF
C
C IMMAGAZZINAMENTO DEI DATI
    IBTF=IBT
    ISTORE(1,9)=IDAY
    ISTORE(2,9)=IBT
    IT=IBT-ISTORE(2,8)+11
    IF(NEWDAY.EQ.1) IT=IT+1440
    IF(IT.GT.721) THEN
        WRITE(1, ('"VUOI ABORTIRE IL PROGRAMMA? (Y/N): "'))
        READ(1,400) NY
        IF(NY.EQ.'Y'.OR.NY.EQ.'YES'.OR.NY.EQ.'1')
    +STOP '** FINE IRREGOLARE DELL'ANALISI***'
    ENDIF
    ISTORE(1,IT)=LMAT(I,6)
    ISTORE(2,IT)=LMAT(I,7)
    ISTORE(3,IT)=LMAT(I,3)
C
C AGGIORNAMENTO DEI DATI NELLA TESTATA
    IF(LMAT(I,6).NE.ZERO) THEN
        IPOS=IPOS+1
        ISTORE(1,2)=JDAY
        ISTORE(1,4)=IBT
        ISTORE(1,7)=IT
        IF(IPOS.EQ.1) THEN
            ISTORE(1,1)=IDAY
            ISTORE(1,3)=IBT
            ISTORE(1,6)=IT
        ENDIF
    ENDIF
    IF(LMAT(I,7).NE.ZERO) THEN
        IPOX=IPOX+1

```

```

ISTORE(2,2)=IDAY
ISTORE(2,4)=IBT
ISTORE(2,7)=IT
IF(IPOX.EQ.1) THEN
  ISTORE(2,1)=IDAY
  ISTORE(2,3)=IBT
  ISTORE(2,6)=IT
ENDIF
ENDIF
ENDIF

C SI RIPETE PER UN'ALTRA RIGA
4  CONTINUE

C SI RIPETE PER UN ALTRO RECORD
IF(NRC.NE.NFI) GO TO 1000

C
C FINE RICERCA DEI DATI
2000 CALL CREA
IYEAR1=LMAT(160,1)/1000.
IDAY1=LMAT(160,1)-IYEAR1*1000.
WRITE(1,*)
WRITE(1,*) 'FINE AL GIORNO:',IDAY1,' DELL'' ANNO',IYEAR1
WRITE(1,*)

C SI PROCEDE CON ALTRI PARAMETRI
IF(I3.GT.0) GO TO 71
5 CONTINUE

C OPZIONE PER RIPETERE L' ANALISI CON ALTRI DATI
IF(IAUTO.EQ.1) WRITE(1,*) ''
WRITE(LU,*)
REWIND ITAPE
WRITE(1,('VUOI IMMAGAZZINARE ALTRI DATI? (Y/N): '))
READ(1,400) NY
IF(NY.EQ.'Y'.OR.NY.EQ.'YES'.OR.NY.EQ.'1') GO TO 10

C FINE REGOLARE DELL'ANALISI
REWIND ITAPE
WRITE(1,*)
WRITE(1,*) '**FINE REGOLARE DELL''ANALISI**'
STOP

C FINE DEL MAIN
END
C ****
C QUESTA SUBROUTINE CREA I DISK FILES
SUBROUTINE CREA

C
INTEGER*4 ISTORE(3,730),ANGDAT(120,6)
CHARACTER*14 NFILE
CHARACTER*3 NY

```

```

COMMON IPO,IPOS,IPOX,IAUTO,ISTORE,ANGDAT,LU
C
C SE CI SONO DATI
    IF(IPO.NE.0) THEN
        IF(IAUTO.NE.1) WRITE(1,*) 'CI SONO', IPO, ' DATI'
C
C RICERCA DEI DATI ANGOLARI
    CALL SEARCH
C
C CREAZIONE DEL FILENAME
    WRITE(NFILE,100) ISTORE(3,3), ISTORE(3,4), ISTORE(1,8)
100   FORMAT('DAT/ROD',I2,I2,I3)
C
C SALTO DELLE RICHIESTE DA INPUT SE IL LAVORO E' AUTOMATICO
    IF(IAUTO.EQ.1) THEN
        NY='YES'
        GO TO 10
    ENDIF
C
C SCRIVE IL DISC FILE RICHIESTO
    WRITE(1,*)
    WRITE(1,*) 'IL FILE ',NFILE,' CONTIENE I SEGUENTI DATI:'
    IF(ISTORE(3,1).EQ.2) WRITE(1,*) '***VALORI REGRESS'
    WRITE(1,*) '***BANDE: S, X E FREQUENZA'
    WRITE(1,*) '***GIORNO INIZIALE:',ISTORE(1,8)
    WRITE(1,*) '***GIORNO FINALE:',ISTORE(1,9)
    WRITE(1,*) '***ANNO:',ISTORE(3,2)
    WRITE(1,*) '***MINUTO INIZIALE:',ISTORE(2,8)
    WRITE(1,*) '***MINUTO FINALE:',ISTORE(2,9)
    WRITE(1,*) '***MODO:',ISTORE(3,5)
    WRITE(1,*) '***DSS TRASMITTENTE:',ISTORE(3,3)
    WRITE(1,*) '***DSS RICEVENTE:',ISTORE(3,4)
    WRITE(1,*) '***ASCENSIONE RETTA:',ISTORE(3,7)
    WRITE(1,*) '***DECLINAZIONE:',ISTORE(3,8)
    WRITE(1,*) '***RTLT:',ISTORE(3,6)
    WRITE(1,*)
    WRITE(1,'(" OK AD IMMAGAZZINARE? <Y/N>: ")')
    READ(1,200) NY
200   FORMAT(A3)
    IF(NY.EQ.'A') STOP '***FINE IRREGOLARE DELL''ANALISI***'
C
C SCRITTURA DEL FILE SE RICHIESTO
10   IF(NY.EQ.'Y'.OR.NY.EQ.'YES'.OR.NY.EQ.'1') THEN
        IF(LU.NE.1) WRITE(LU,300) NFILE,ISTORE(1,8),ISTORE(1,9),
        +ISTORE(3,2),ISTORE(2,8),ISTORE(2,9),ISTORE(3,5),ISTORE(3,3),
        +ISTORE(3,4),ISTORE(3,7),ISTORE(3,8),ISTORE(3,6)
300   FORMAT(1X,A16,11(I10))
        WRITE(1,*)
        WRITE(1,*) 'SCRITTURA DEL FILE ',NFILE
        ISTORE(1,5)=IPOS
        ISTORE(2,5)=IPOX
        ISTORE(3,9)=IPO
        OPEN(70,FILE=NFILE,IOSTAT=IOSO,ERR=20)

```

```

        WRITE(70,*) ISTORE
        CLOSE(70,IOSTAT=IOSC,ERR=30)
                           ELSE
        WRITE(1,*) 'FILE ',NFILE,' NON CREATO'
        ENDIF
C
C REINIZIALIZZAZIONE DEI BUFFERS
        IPO=0
        IPOS=0
        IPOX=0
        DO 1 II=1,3
          DO 1 JJ=1,730
            ISTORF(II,,JJ)=0
1      CONTINUE
        ENDIF
C
C RITORNO AL MAIN
        RETURN
C
C ERRORE IN OPEN FILE 70
        20 WRITE(1,*) '**ERRORE IN OPEN FILE ',NFILE,' #',IOS0,'**'
          STOP
C
C ERRORE IN CLOSE FILE 70
        30 WRITE(1,*) '**ERRORE IN CLOSE FILE ',NFILE,' #',IOSC,'**'
          STOP
C
C FINE DI CREA
        END
C ****
C QUESTA SUBROUTINE CERCA I DATI ANGOLARI
        SUBROUTINE SEARCH
C
        INTEGER*4 ISTORE(3,730),ANGDAT(120,6)
        INTEGER*4 SUMMIN,MINMED,IDHM,FDHM
        CHARACTER*3 NY
        COMMON IPO,IPOS,IPOX,IAUTO,ISTORE,ANGDAT,LU
C
C RICERCA DEI DATI ANGOLARI
        SUMMIN=ISTORE(2,8)+ISTORE(2,9)+1.
        IF(ISTORE(1,8).NE.ISTORE(1,9)) SUMMIN=SUMMIN+1440.
        MINMED=SUMMIN/2
        IF(MINMED.GT.1440) MINMED=MINMED-1440
        D4=10000
        I60=60
        IDHM=ISTORE(1,8)*D4+MINMED/I60*100+MOD(MINMED,I60)
        KK=0
        DO 1 K=1,120
          IF(ISTORE(3,2).LT.ANGDAT(K,1)/1000) GO TO 10
          FDHM=(ANGDAT(K,1)-ISTORE(3,2)*1000)*D4+ANGDAT(K,2)/100
          IF(FDHM.LT.IDHM) GO TO 1
          KK=K
1

```

```

      GO TO 10
1 CONTINUE
C
C DATI NON TROVATI
10 IF(KK.EQ.0) THEN
    WRITE(1,*) '**DATI ANGOLARI NON TROVATI!**'
    IF(LU.NE.1) WRITE(LU,*) 'DATI ANGOLARI NON TROVATI'
    IF(IAUTO.NE.1) THEN
        WRITE(1,'("VUOI ABORTIRE IL PROGRAMMA? <Y/N>: ")')
        READ(1,200) NY
200   FORMAT(A3)
        IF(NY.EQ.'Y'.OR.NY.EQ.'YES'.OR.NY.EQ.'1')
+STOP '**IRREGOLARE FINE DEL PROGRAMMA**'
        ENDIF
        ISTORE(3,7)=ANGDAT(120,5)
        ISTORE(3,8)=ANGDAT(120,4)
        ISTORE(3,9)=ANGDAT(120,3)
        RETURN
    ENDIF
    KKK=KK-1
    IF(KKK.EQ.0) THEN
        ISTORE(3,7)=ANGDAT(1,5)
        ISTORE(3,8)=ANGDAT(1,4)
        ISTORE(3,9)=ANGDAT(1,3)
        RETURN
    ENDIF
C
C SI RIEMPIE IL BUFFER
    FS1=ANGDAT(KKK,2)-(ANGDAT(KKK,2)/100)*100
    FH1=ANGDAT(KKK,2)/D4
    FM1=(ANGDAT(KKK,2)-FH1*D4)/100
    FS2=ANGDAT(KK,2)-(ANGDAT(KK,2)/100)*100
    FH2=ANGDAT(KK,2)/D4
    FM2=(ANGDAT(KK,2)-FH2*D4)/100
    ITS=30
    ITD=IDHM/D4
    ITH=(IDHM-ITD*D4)/100
    ITM=(IDHM-ITD*D4-ITH*100)
    IF(FH2-FH1.LT.0) THEN
        FH2=FH2+24
        IF(IDHM-FDHM.LT.0) ITH=ITH+24
    ENDIF
    T2=FS2/60.+FM2+FH2*60.
    T1=FS1/60.+FM1+FH1*60.
    T=ITS/60.+ITM+ITH*60.
    DT=T2-T1
    IF(DT.EQ.0) THEN
        WRITE(1,*) '**RIPETIZIONE NEI DATI ANGOLARI**'
        IF(LU.NE.1) WRITE(LU,*) 'RIPETIZIONE NEI DATI ANGOLARI'
        IF(IAUTO.NE.1) THEN
            WRITE(1,'("VUOI ABORTIRE IL PROGRAMMA? <Y/N>: ")')
            READ(1,200) NY
            IF(NY.EQ.'Y'.OR.NY.EQ.'YES'.OR.NY.EQ.'1')

```

```
+STOP '**FINE IRREGOLARE DELL'' ANALISI**'
ENDIF
ISTORE(3,7)=ANGDAT(KK,5)
ISTORE(3,8)=ANGDAT(KK,4)
ISTORE(3,9)=ANGDAT(KK,3)
ENDIF
ST=ANGDAT(KK,5)-ANGDAT(KKK,5)
ISTORE(3,7)=ST/DT*(T-T1)+ANGDAT(KKK,5)
ST=ANGDAT(KK,4)-ANGDAT(KKK,4)
ISTORE(3,8)=ST/DT*(T-T1)+ANGDAT(KKK,4)
ST=ANGDAT(KK,3)-ANGDAT(KKK,3)
ISTORE(3,6)=(ST/DT*(T-T1)+ANGDAT(KKK,3))/10

C
C RITORNO ALLA CHIAMATA
RETURN
C
C FINE DI SEARCH
END
```

TAB. 1

REGRESS MEASUREMENT STRUCTURE

- 1 TIME 1: UTC (seconds 1950)
- 2 TIME 2: composite word containing UTC coded as year, day of year, hour, minute, second and fractions of second; these information are contained in the decimal part of time 2 as:

YYDDDHMMSSfffff

- 3 IDENTIFICATION WORD: composite word containing sampling rate in hundredths of seconds in the first seven decimal figures; the 8th figure represents the downlink band (1=5, 2=X), the 9th one the tracking network (DSN=1), the 10th and 11th the transmitting station, the 12th and 13th the receiving station, the 14th the data type (1=Doppler), the 15th the tracking link mode (2=two way, 3=three way), the last figures are not used; the scheme is:

1.5555555BNTRRKW

- 4 OBSERVABLE: observed frequency shift in Hertz, (same quantity as in the ATDF tapes).
- 5 FREQUENCY: oscillator frequency in Hz. The transmitted frequency is obtained multiplying FREQUENCY by 96.
- 6 PASS IDENTIFIER: composite word containing spacecraft identification code.
- 7 COMPUTED: frequency shift predicted by ODP
- 8 RTLT: round trip light time in seconds
- 9 HOUR ANGLE: composite word containing the spacecraft hour angle in degrees, minutes, seconds and fractions of seconds in the first figures; the code is:

1.DDMMSSffff

- 10 DECLINATION: composite word containing spacecraft declination in degrees, minutes, seconds and fractions of seconds; the code is the same as in item 9.
- 11 AZIMUTH: composite word containing spacecraft azimuth in degrees, minutes, seconds and fractions of seconds; code as in item 9.

- 12 ELEVATION AT RECEIVING TIME: composite word containing spacecraft elevation at the receiving time in degrees, minutes, seconds and fractions of seconds; code as in item 9;
- 13 ELEVATION AT TRANSMITTING TIME: composite word containing spacecraft elevation at the transmitting time; code as in item 9.
- 14 DERIVATIVE OF THE ELEVATION AT RECEIVING TIME: in deg./s
- 15 DERIVATIVE OF THE ELEVATION AT TRANSMITTING TIME: in deg./s
- 16 RESIDUAL: Doppler residual in Hz, computed from OBSERVABLE minus COMPUTED (item 4 minus item 7).
- 17 REJECTION CODE: if this code is 0 the data are ok.
- 18 WEIGHT: data quality indicator (used by ODP).
- 19 CALIBRATION: media calibration to Doppler residuals (in Hz).
- 20 CALIBRATED RESIDUAL: calibrated residual in Hz. It is computed by subtracting: RESIDUAL minus CALIBRATION (items 16 and 19).

TAB. 2

STRUCTURE OF REGRESS RECORDS

rows	----->	1	6	9	33	57
columns		N1	N2	TIME TAG 1	TIME TAG 2	ID. WORD
		N1	N2	OBSERVABLE	FREQUENCY	PASS ID.
	V	N1	N2	COMPUTED	RTLT	HOUR ANGLE
		N1	N2	DECLINATION	AZIMUTH	ELEV. T3
		N1	N2	ELEV. T1	ELEV. DER. T1	ELEV. DER.T3
		N1	N2	RESIDUAL	REJECTION	WEIGHT
		N1	N2	CALIB. COMP.	MODELS	TIME TAG 1
	
		.	.	omissis	.	.
100

TAB. 3

EXAMPLE OF REGRESS RECORD

The data start from time 20h 00' 29" of the DOY 308 year 1980

```

1 1 .97328162999999999+009 .803082000299999998+016 .100060001114121300+017
1 2-.269094662833319999+005 .220277400000000000+008 .103080310204800000+017
1 3-.269090225907072255+005 .101894300547065213+005 .410241037489606019+002
1 4-.610047258413681025-001 .236355807440611173+003 .0000000000000000000000
1 5 .544776425522538426+002-.283824054044811239-002 .164946371770699485-003
1 6-.443692624774428168+000 .00000000000000000000 .0000000000000000000000
1 7 .00000000000000000000 .00000000000000000000 .97328162999999999+009
1 8 .803082000299999998+016 .100060002114121300+017-.98668027699990000+005
1 9 .220277400000000000+008 .103080310204800000+017-.986664161639321474+005
1 10 .101894300547065213+005 .410241037489606019+002-.610047258413681014-001
1 11 .236355807440611173+003 .00000000000000000000 .544776425522538426+002
1 12-.283824054044811239-002 .164946371770699485-003-.161153606685252271+001
1 13 .00000000000000000000 .00000000000000000000 .0000000000000000000000
1 14 .00000000000000000000 .97328162999999999+009 .803082000299999998+016
1 15 .100060001114141200+017-.26915640899980000+005 .220277400000000000+008

```

. . . omissis

```

1 94 .00000000000000000000 .97328174999999999+009 .803082002299999998+016
1 95 .100060001114121300+017-.268720277666650000+005 .220277400000000000+008
1 96 .103080310204800000+017-.268715821903272889+005 .101894286495735869+005
1 97 .415250900514604227+002-.609566732205611566-001 .236819925387191006+003
1 98 .00000000000000000000 .544943592287294470+002-.285344413867476923-002
1 99 .113775830962588772-003-.445576337711003134+000 .0000000000000000000000
1 100 .00000000000000000000 .00000000000000000000 .0000000000000000000000

```

TAB. 4

STRUCTURE OF STANDARD RECORDS

1	YYDDD	year and day
2	HHMMSS	hour, minute and second
3	FREQCY	oscillator frequency in Hz
4	TTRRNM	trans. and rec. stations, network and mode
5	ELupELdw	elevation in up and down link in degrees
6	S-RES	S-band residual in mmHz
7	X-RES	X-band residual in mmHz
8	S-3/11**X	quantity used in plasma calibration
9	S-OBS	S-band observable (in Hz)
10	X-OBS	X-band observable (in Hz)
11	REJCOD	rejection code
12	WEIGHT	datum weight
13		not used
14		not used
15		not used

TAB. 5

DATA TRANSFER FROM REGRESS FILE TO STANDARD FILE

INPUT DATA	OUTPUT DATA
1 TIME 1	not transferred
2 TIME 2	{ 1) YYDDD 2) HHMMSS}
3 ID. WORD	{ band indicator 4) TTRRMM}
4 OBSERVABLE	9) S-OBS or 10) X-OBS
5 FREQUENCY	3) FREQCY
6 PASS ID.	not transferred
7 COMPUTED	not transferred
8 RTLT	not transferred
9 HOUR ANGLE	not transferred
10 DECLINATION	not transferred
11 AZIMUTH	not transferred
12 ELEVATIONS	5) ELupELdw
13	
14 EL. DERIVATIVES	not transferred
15	
16 RESIDUAL	6) S-RES or 7) X-RES
17 REJECTION CODE	11) REJCOD
18 WEIGHT	12) WEIGHT
19 CALIBRATION	not transferred,
20 CAL. RESIDUAL	not transferred.

TAB. 6

EXAMPLE OF STANDARD RECORD

Data start from time 20h 00' 29" of the DOY 308 year 1980

1	80308	200029	22027740	141213	54473792	-443692	-1611536	-4182
	-26909	-98668		0	0	0	0	0
2	80308	200029	22027740	141412	54473792	-447566	-1624393	-4549
	-26915	-98690		0	0	0	0	0
3	80308	200029	22027740	144213	54472920	-450149	-1638823	-3197
	-31147	-114208		0	0	0	0	0
4	80308	200029	22027740	144313	54472920	-446804	-1639150	236
	-31147	-114208		0	0	0	0	0
5	80308	200129	22027740	141213	54483776	-442122	-1610828	-2805
	-26890	-98599		0	0	0	0	0
6	80308	200129	22027740	141412	54483776	-446126	-1623059	-3473
	-26896	-98621		0	0	0	0	0
7	80308	200129	22027740	144213	54482936	-447568	-1638656	-661
	-31130	-114146		0	0	0	0	0
8	80308	200229	22027740	141213	54493752	-445576	-1602485	-8534
	-26872	-98530		0	0	0	0	0
9	80308	200229	22027740	141412	54493760	-447826	-1620098	-5981
	-26878	-98553		0	0	0	0	0
10	80308	200229	22027740	144213	54492960	-446743	-1636628	-389
	-31114	-114085		0	0	0	0	0
. . . omissis								
160	80308	204029	22027740	141412	53653088	-445258	-1612198	-5567
	-26197	-96058		0	0	0	0	0

EXAMPLE OF REGRESS TABLE

Doppler residuals available for the DOY 309 of the year 1980

TAB. 7

TAB. 8

ANGULAR DATA STRUCTURE

- 1 - TIME TAG (high part), coded as YYDDD
- 2 - TIME TAG (low part), coded as HHMMSS
- 3 - RTLTx10 it is given in seconds with an approximation of .1 sec; the stored value is IFIX(RTLTx10.)
- 4 - RAx100 the right ascension is given in degrees with an approximation of .01 degrees; the stored value is IFIX(RAx100.)
- 5 - DECx100 the declination is given in degrees with an approximation of .01 degrees; the stored value is IFIX(DECx100.)
- 6 - ELOx100 the elongation is given in degrees with an approximation of .01 degrees; the stored value is IFIX(ELOx100.)

TAB. 9

LOGICAL FORMAT OF DOPPLER DATA FILES (ROD)

rows ---->	1	2	3
columns : 1	S INITIAL DAY	X INITIAL DAY	DATA ID. (1=A 2=R)
: 2	S FINAL DAY	X FINAL DAY	YEAR
: 3	S INITIAL MINUTE	X INITIAL MINUTE	TRANSMITTING DSS
4	S FINAL MINUTE	X FINAL MINUTE	RECEIVING DSS
5	# of S-band DATA	# of X-band DATA	MODE
6	LOCATION OF THE FIRST S-BAND ITEM	LOCATION OF THE FIRST X-BAND ITEM	RTLT
7	LOCATION OF THE LAST S-BAND ITEM	LOCATION OF THE LAST X-BAND ITEM	RIGHT ASCENSION
8	INITIAL DAY	INITIAL MINUTE	DECLINATION
9	FINAL DAY	FINAL MINUTE	# of S or X DATA
10	0	0	0
11	1	1	1
.	S-BAND DATA :	X-BAND DATA :	OSCILLATOR FREQUENCY :
.	mmHz :	mmHz :	Hz :
730	V	V	V

N.B.:

- 1) S and X stand for S-band and X-band respectively
- 2) The value of the item DATA IDENTIFIER is 1 for ATDF data and 2 for REGRESS data

TAB. 10

FILE DAT/ROD1414309

1	309	309	2
2	309	309	80
3	903	903	14
4	1347	1347	14
5	384	384	2
6	11	11	10187
7	455	455	18571
8	309	903	-22
9	309	1347	384
10	0	0	0
11	-1716015139	2147483647	22027744
12	2147483647	2147483647	22027744
13	2147483647	2147483647	22027744
14	-458095	-1670888	22027720
15	-457467	-1671856	22027720
16	-457156	-1669117	22027720
17	-453513	-1655412	22027720
.	.	.	.
730	0	0	0

FIGURE CAPTIONS

Fig. 1 The Deep Space Network stations.

Fig. 2a Flow chart of the program DECODEREGRES.

2b Zoom of block A of the previous flow chart.

Fig. 3 Flow chart of the program STATREGRES.

Fig. 4 Output of the program PLOTREGRES.

Fig. 5 Flow chart of the program PLOTREGRES.

Fig. 6 Flow chart of the program FFREGRES.

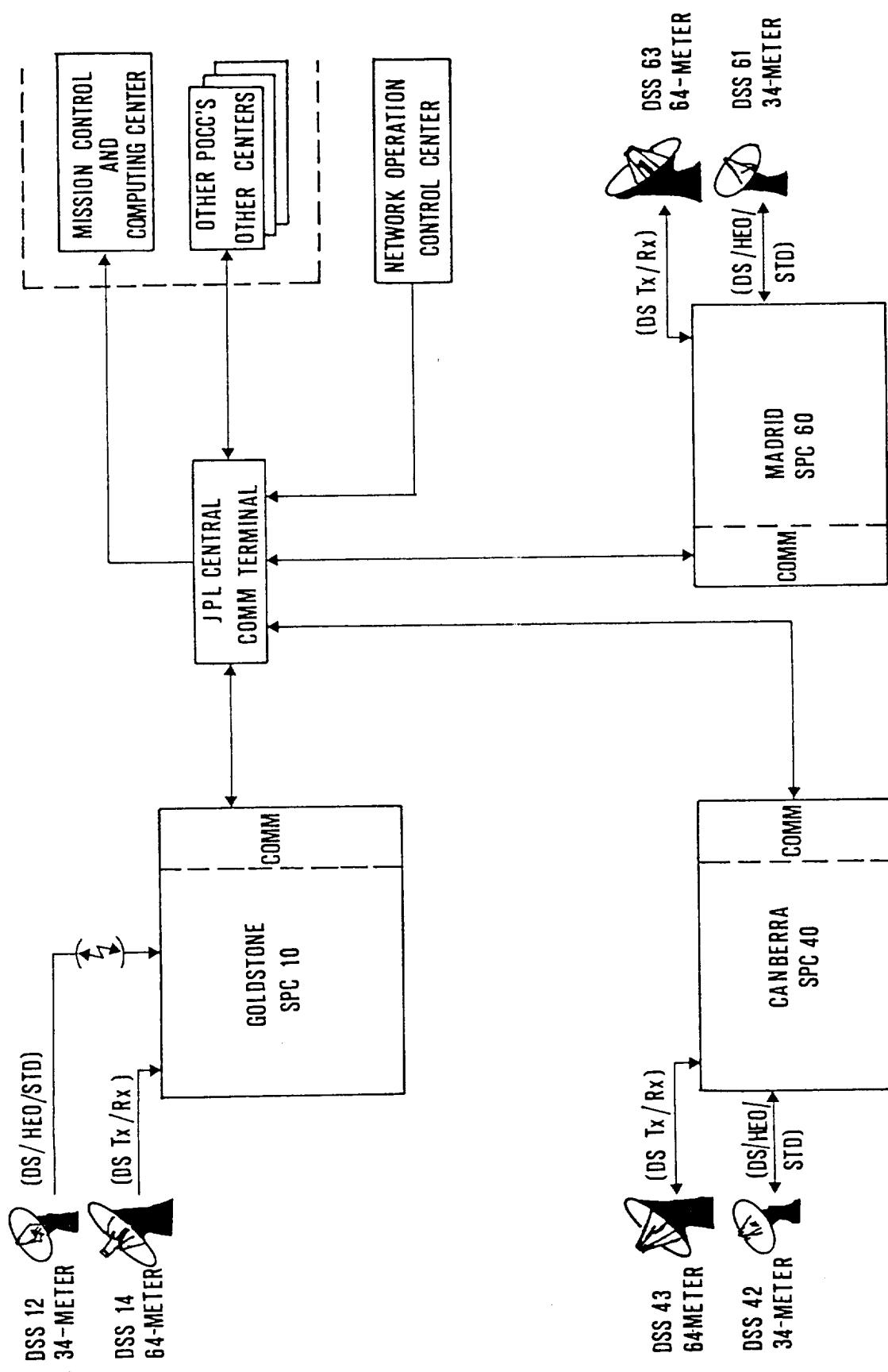


FIG. 1

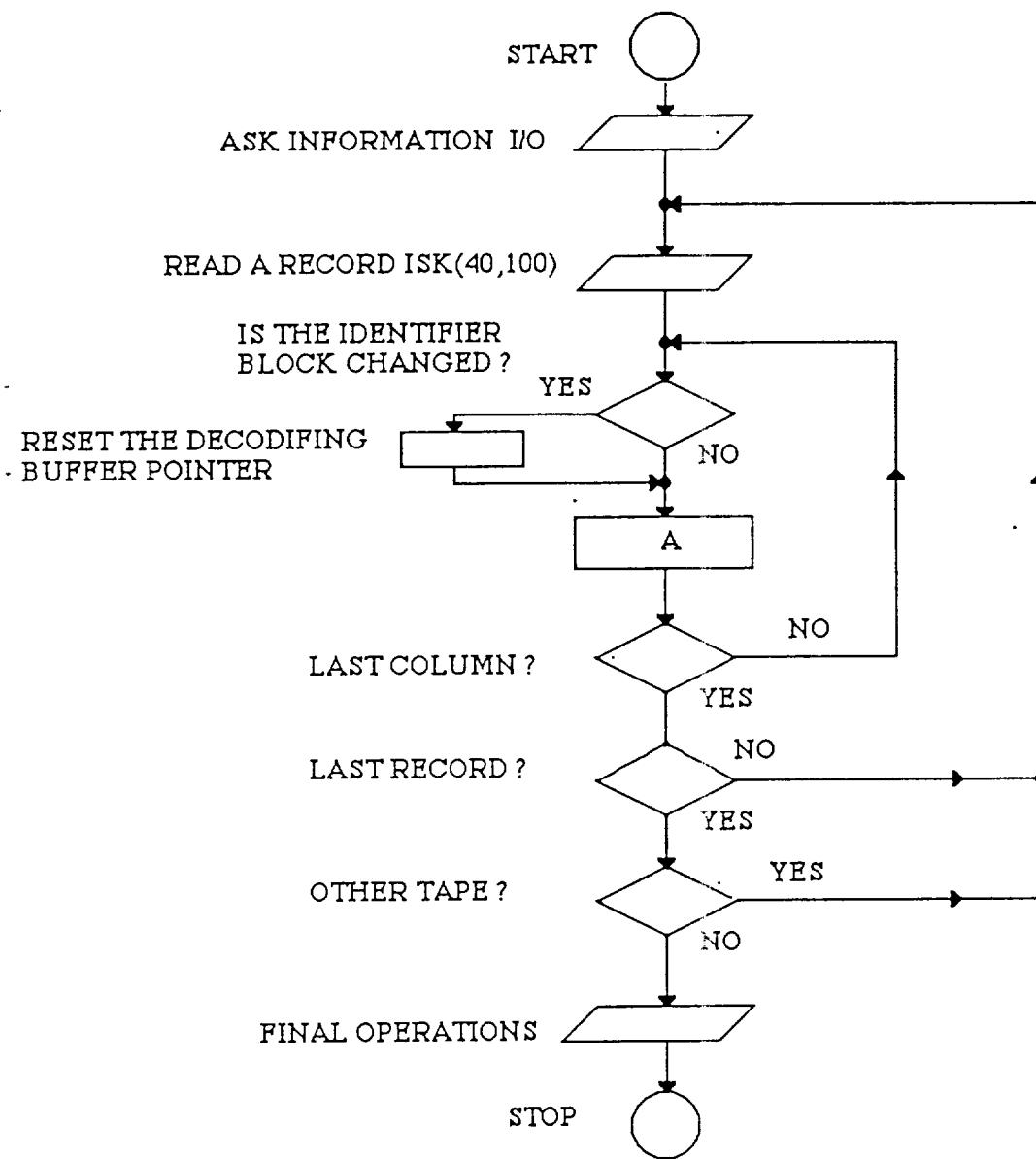


FIG. 2 a

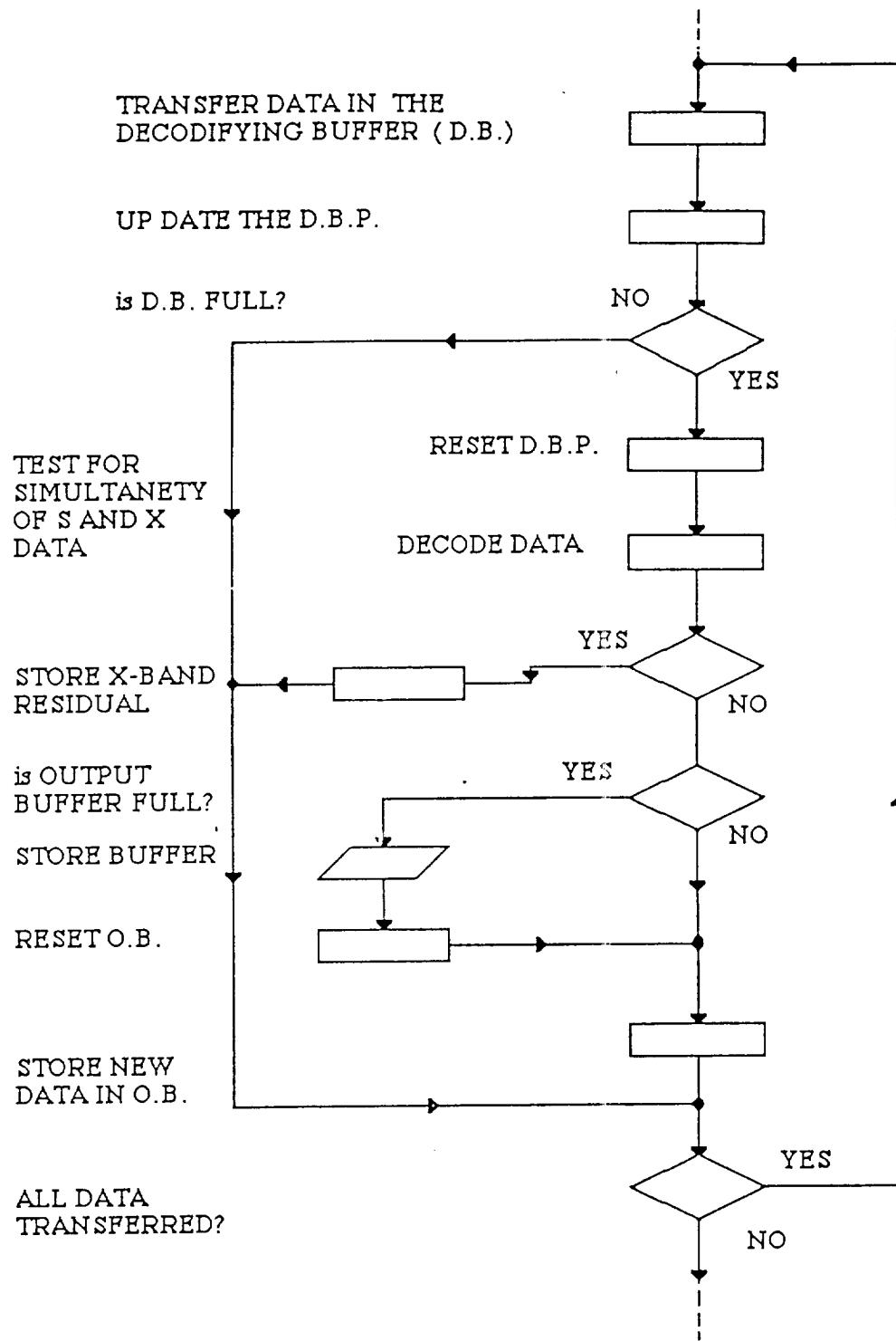


FIG. 2 b

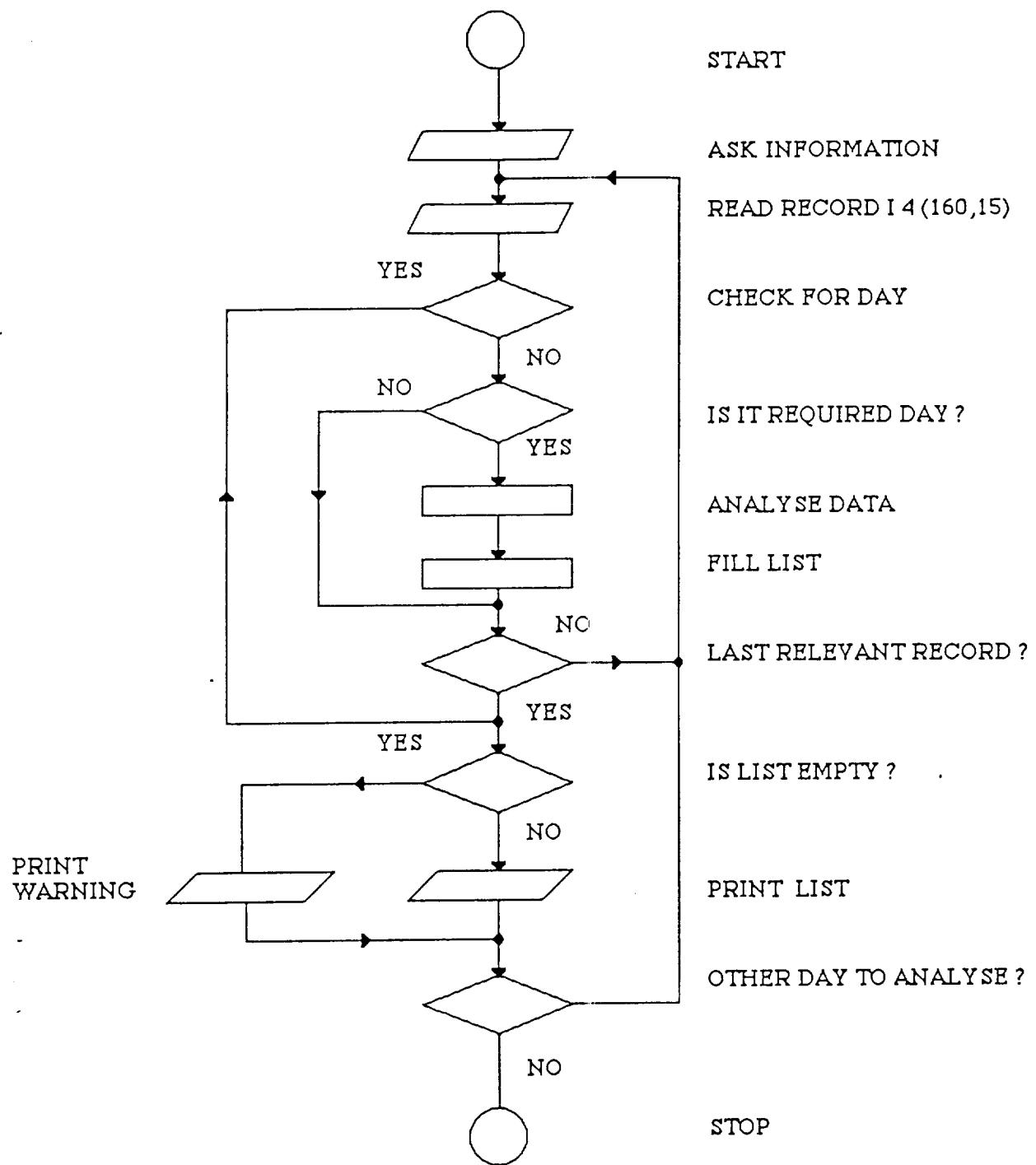
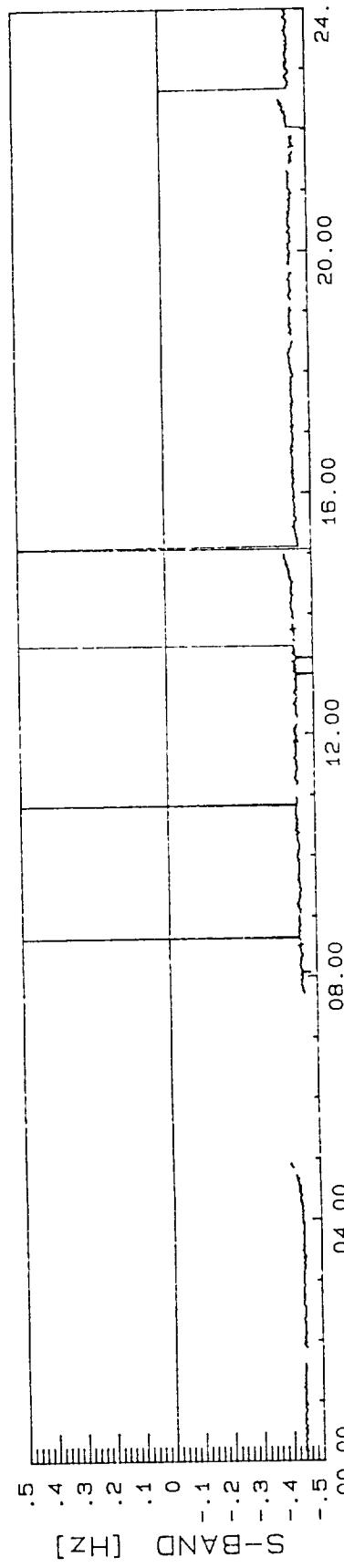
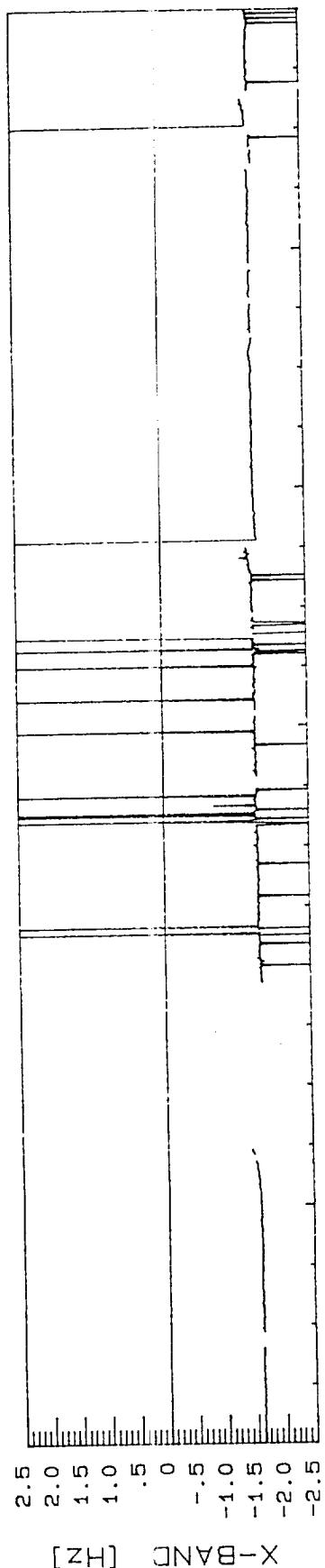
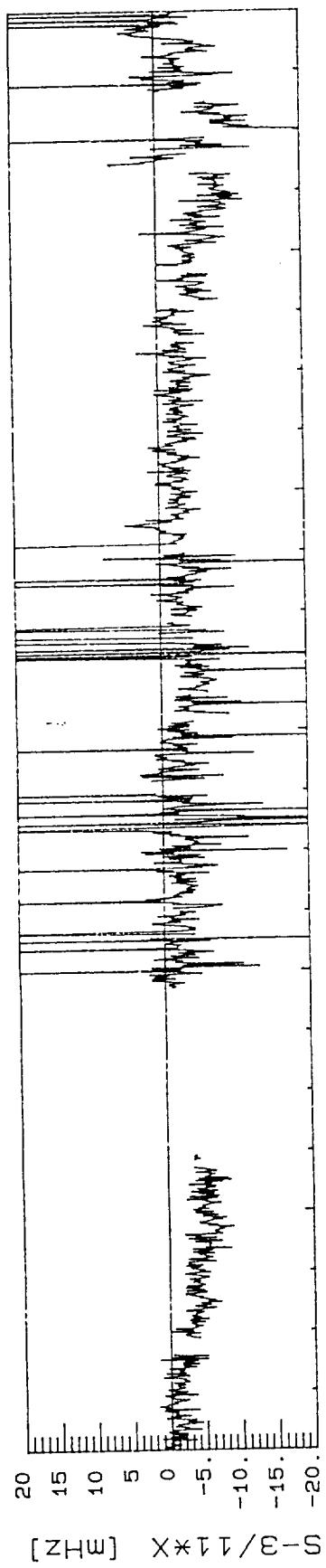


FIG. 3

DAY = 309

MODE = 2



VOYAGER 1980

REGRESS FILES

FIG. 4

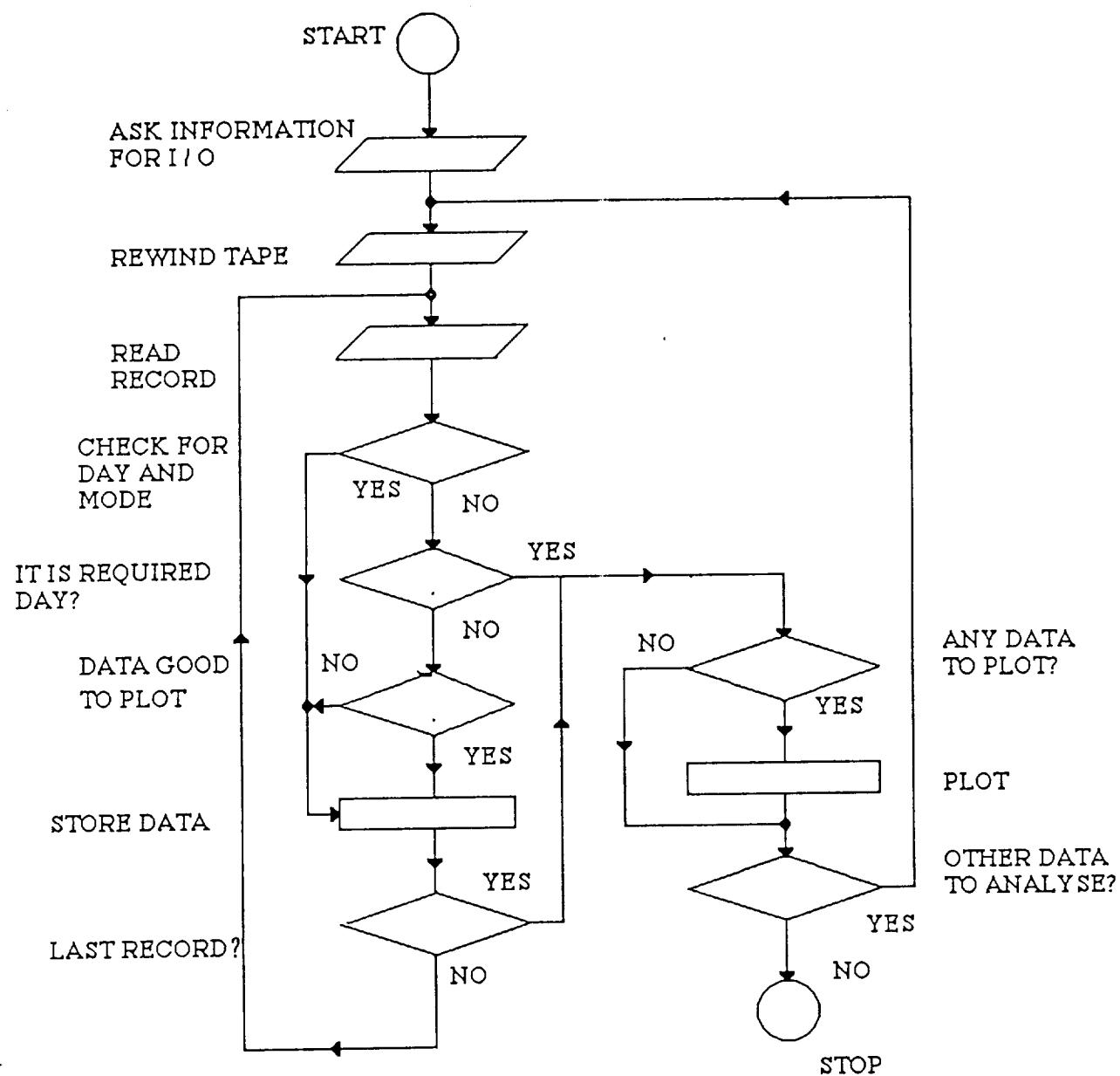


FIG. 5

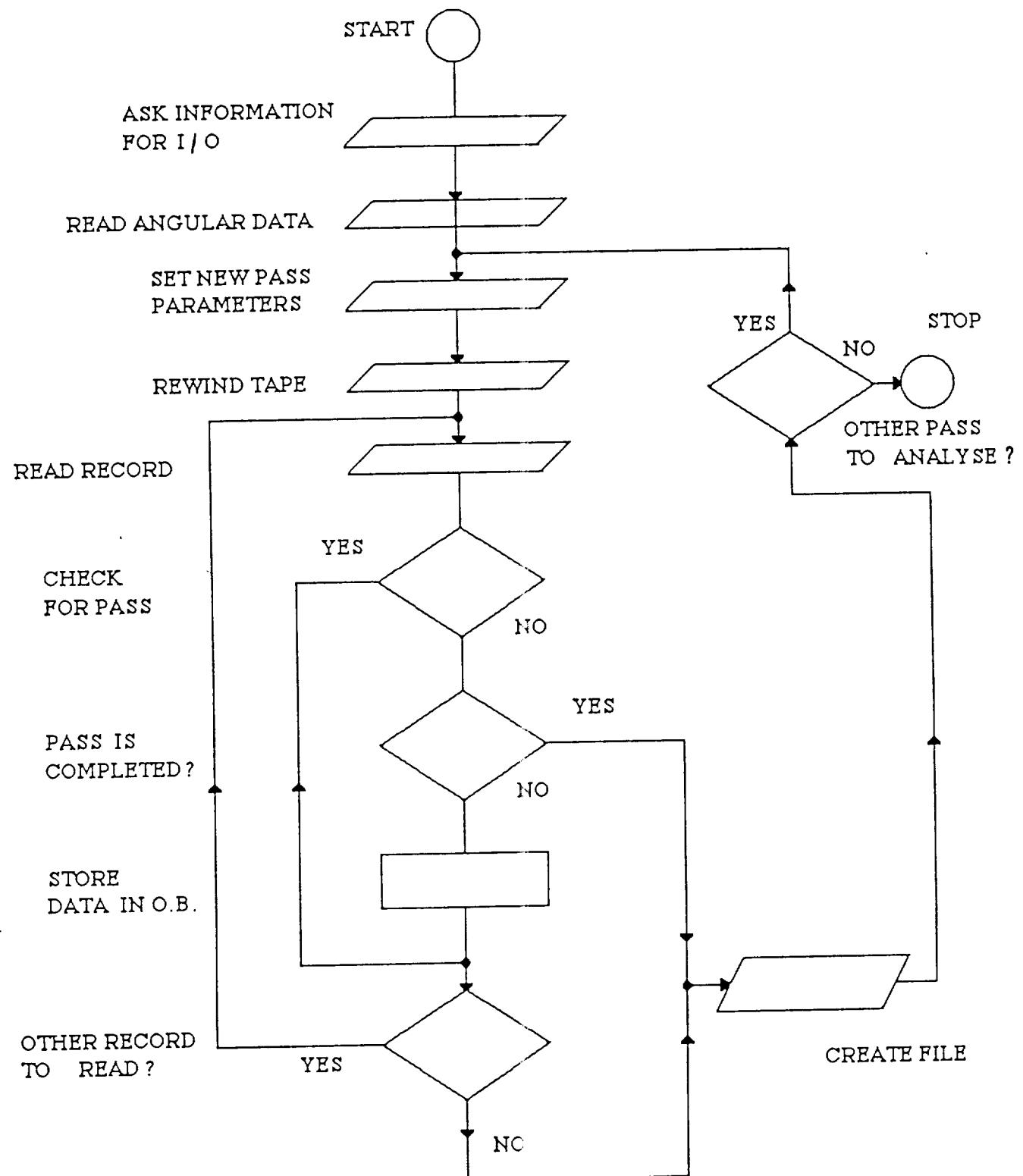


FIG. 6

